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SESAR SOLUTION PJ.02- W2-14.5 CONTEXTUAL NOTE V3

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13 AART

14 AIRPORT AIRSIDE AND RUNWAY THROUGHPUT

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17 under grant agreement No 874477 under European Union's Horizon 2020 research and innovation
18 programme.



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20

21 **Abstract**

22 This V3 Contextual note provides SESAR Solution PJ.02-W2-14.5 description for industrialisation
23 consideration.

24

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59 1 Purpose

60 This contextual note describes the solution PJ.02-W2-14.5 with a summary of the results stemming
61 from R&D activities contributing to deliver it. It provides (to both those external and internal to the
62 SESAR programme) an overview of the solution in terms of scope, main operational and performance
63 benefits, relevant system impacts and recommends additional activities that should be conducted
64 during the industrialisation phase or as part of deployment.

65 This contextual note complements the solution Data Pack comprising the SESAR deliverables required
66 for industrialisation and deployment.

67

2 Improvements in Air Traffic Management (ATM)

2.1 Solution description & Scope

Initial R&D work on “Increased Glide Slope to Second Runway Aiming Points (IGS-to-SRAP)” started in **SESAR 2020 Wave 1 solution PJ02-02** which was grouping five different new approach procedures. At the end of Wave 1, the solution PJ02-02 was split into five different solutions.

This contextual note is about solution PJ.02-W2-14.5 solution only, “Increased Glide Slope to Second runway aiming point (IGS-to-SRAP)”. The solution is limited to the cases when the distance between the two thresholds is at least 1100m.

PJ02 Wave 2 built on previous work to further validate the solution to V3 maturity level.

Increased Glide Slope to Second Runway Aiming Point (IGS-to-SRAP) will allow inbound aircraft reducing noise footprint impact in the surrounding areas of the airport and possibly runway occupancy time and/or taxi-in time, while also allowing potential increased runway capacity (via optimised wake separations).

The IGS-to-SRAP concept is a published approach procedure, enabling aircraft to land on a second further runway aiming point (with associated runway ground markers, lights and visual aids) and using a glide slope higher than the one to the first threshold.

The IGS-to-SRAP procedure is designed with a glide slope higher than the nominal one operated for the first aiming point. See Figure 1 and Figure 2.

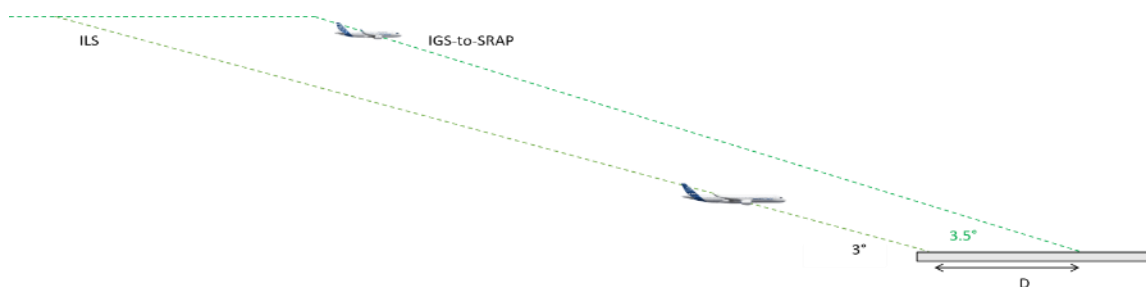


Figure 1: IGS-to-SRAP procedure with one interception altitude ($D \geq 1100m$)

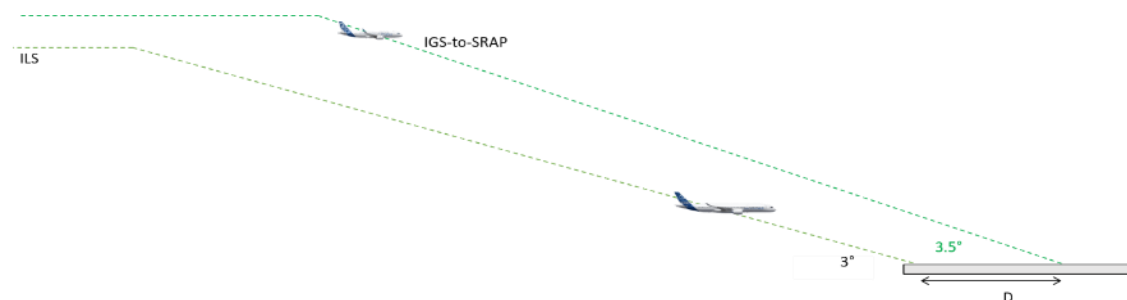


Figure 2: IGS-to-SRAP procedure with two interception altitudes ($D \geq 1100m$)

91 Choosing an IGS-to-SRAP approach (over the conventional one) could be the result of the best
 92 compromise between available runway length, preferential runway exit use, noise, wake turbulence
 93 separation constraints, and the runway occupancy time.

94 **2.2 Relevant Operational Environments**

OEs	Sub Operating Environments	Definition
Airport	Very Large Airport	Airports with more than 250k movements per year
	Large Airport	Airports with more or equal than 150k and less or equal than 250k
	Medium Airport	Airports with more or equal than 40k and less than 150k movements per
TMA	Very High Complexity	TMA with an Aggregated Traffic Complexity Score greater or equal to 10 or, if score is not available, with a number of serviced IFR flights greater or equal to 200000 per year.
	High Complexity	TMA with an Aggregated Traffic Complexity Score greater or equal to 6 and less than 10 or, if score is not available, with a number of serviced IFR flights greater or equal to 100000 and less than 200000
	Medium Complexity	TMA with an Aggregated Traffic Complexity Score greater or equal to 2 and less than 6 or, if score is not available, with a number of serviced IFR flights greater or equal to 20000 and less than 100000 per year.

95

96 **2.3 Expected Benefits**

97 The following KPAs express benefits from IGS-to-SRAP:

- 98 • **Environment / Fuel Efficiency** (reduction kg of fuel per flight);
- 99 • **Environment / Noise and Local Air Quality** (reduction of affected residents around airport
 100 with large fraction of MEDIUM aircraft);
- 101 • **Airport Capacity (Runway Throughput Flights/Hour)** (increase in movements/hour). The
 102 benefits are highly linked to local airport configuration (such as exit locations) and to local
 103 traffic mix.
- 104 • **Cost Efficiency / Human Performance** (increase in movements/hour).

3 Operational Improvement Steps (OIs) & Enablers

107 Applicable OI Step:

108 **AO-0331** — Enhanced approach operations using an increased glide slope to a second runway
 109 aiming point (IGS-to-SRAP)

111 Dependent OI Step:

112 **None**

114 Required Enablers:

115 **AERODROME-ATC-102** - Aerodrome ATC system to support final approach operations (distinguish
 116 approach procedures)

117 **AIRPORT-56** - Runway marking and lighting for IGS-to-SRAP/IGS-to-SRAP approach procedures

118 **APP ATC 170** - Approach ATC system upgraded to support approach procedure assignment

119 **HUM-024** - Flight Crew new role for handling IGS-to-SRAP approach

120 **HUM-033** – ATC new role for handling IGS-to-SRAP approach

121 **REG-0533** - Regulatory provisions for Increased Glide Slope to Second Runway Aiming Point
 122 operations (IGS-to-SRAP)

123 **STD-112** - Update of EASA and ICAO regulatory frameworks for new visual ground aids (SRAP)

125 Optional Enablers:

126 **AERODROME-ATC-94** - Aerodrome ATC System to support Second Runway Aiming Point (SRAP)
 127 operations (separation delivery)

128 **APP ATC 163** – APP ATC System to support Second Runway Aiming Point (SRAP) operations
 129 (separation delivery).

130 **A/C-86** - On-board assistance to aircraft energy management

131 **A/C-87** - On-board assistance to flare

133 The two enablers for ATC systems are qualified as optional, however in case of airports with
 134 complex separation minima scheme in high traffic environment, these enablers become required
 135 as the controllers cannot have in mind the complex separation minima to apply.

137 The two aircraft enablers are qualified as optional. However, depending on the value of the slope
 138 and on the type of aircraft, they may become required. For example, trials made in the scope of
 139 VLD1 showed that Dassault aircraft do not need any enabler for slope up to 4.4deg, while Airbus
 140 considers that their aircraft may require assistance above 3.5deg.

142 Applicable Integrated Roadmap Dataset is DS23.

143

4 Background and validation process

144 The solution has been validated through a series of validations activities performed in SESAR 2020
145 Wave 1 and Wave 2.

146 SESAR2020 Wave 1 Validation activities

147 • Fast-time simulations

- 148 • A fast time simulation about IGS-to-SRAP at Barcelona Airport assessed the performance
149 of IGS-to-SRAP.
- 150 • A fast time simulation evaluated the impact of IGS-to-SRAP procedures on both noise
151 emission and overall airport capacity.
- 152 • A fast time simulation assessed the benefits of IGS-to-SRAP in terms of runway capacity
153 and fuel burn savings with environmental impact due CO2 reductions.

154 • Real-time simulations

- 155 • Two real time simulations on Paris CDG Airport assessed, from the air traffic controllers'
156 point of view, the use of IGS-to-SRAP, in comparison to the conventional approach
157 procedure only (ILS featuring a 3° glideslope)
- 158 • A real time validation assessed IGS-to-SRAP runway aids from pilots' point of view, via
159 flight cockpit simulations using high level professional Level D/Type 7 flight crew training
160 simulator. The simulator of the type Airbus A319 has full motion, control loading and a
161 configurable visual system.
- 162 • Two real time simulations assessed the use of the two aircraft enablers (energy
163 management and assistance to flare) on an Airbus aircraft cockpit simulator.

164 SESAR2020 Wave 2 Validation activities

165 • Real-time simulations

- 166 • A real time simulation assessed the ways proposed to air traffic controllers, to manage the
167 non-nominal situations involving aircraft flying IGS-to-SRAP procedures. These non-
168 nominal situations were the loss of the controller separation support tool, the go-
169 around/missed approaches and cases when an aircraft was not performing the
170 expected/cleared approach procedures (i. e. ILS approach when IGS-to-SRAP expected or
171 cleared, or IGS-to-SRAP when ILS expected or cleared).
- 172 • A real time simulation for pilots assessed the two proposed solutions for IGS-to-SRAP
173 runway lighting, steady and switching, via flight cockpit simulations using high level
174 professional Level D/Type 7 flight crew training simulator. The simulator of the type Airbus
175 A319 has full motion, control loading and a configurable visual system. The proposed
176 solution for the PAPI for IGS-to-SRAP was as well evaluated.
- 177 • A real time simulation for pilots assessed several proposed solutions for IGS-toSRAP
178 runway marking, via flight cockpit simulations using high level professional Level D/Type 7
179 flight crew training simulator. The simulator of the type Airbus A319 has full motion,
180 control loading and a configurable visual system. The proposed solution for the PAPI for
181 IGS-to-SRAP was as well evaluated.

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- Following the results of the simulation about lighting, a last real time simulation for pilots assessed the steady solution for lighting with pilots that had never seen the other solution (switching). The simulator was the same as before. The proposed solution for the PAPI for IGS-to-SRAP was as well evaluated.
- 186
- **Flight trials**
- 187
- A flight trial campaign took place at Twente airport, as part of VLD1 project, involving both airline aircraft (non revenue flights) and pilots, and test aircraft and pilots. It assessed, under VMC conditions, the marking, dual PAPI set-up and runway designator increment, as recommended from Wave 2 flight simulations and the PAPI for IGS-to-SRAP. However, there were no IGS-to-SRAP Approach Lighting system, neither ATC service available at Twente for these trials. The navigation guidance was based on a (temporary) GBAS GAST-D ground station, which was compatible for a test flight, having the test aircraft used a GAST-D onboard receiver and the Airline aircraft (A319ceo and B737Max8) using GAST-C avionics.
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- A flight trial took place at Rome Ciampino airport, as part of VLD1, to assess different glide slope angles and the two aircraft enablers developed by Honeywell, with solutions different from the ones evaluated in Wave 1 by Airbus.
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- 199

200 5 Results and performance achievements

201 5.1 Results from ATC side

202 Wave 1 assessed the use of IGS-to-SRAP approach procedures in nominal situations. The results are
 203 the following:

- 204 • The proposed ATC HMI for IGS-to-SRAP was found usable and acceptable for the controllers.
 205 The supporting ATC HMI design of the Air Surveillance Display was adapted to enable the
 206 Approach Controllers to select and record the expected / cleared approach. On the Tower
 207 Runway Control CWP the HMI was adapted to facilitate identification of which traffic is cleared
 208 on which procedure.
- 209 • Thanks to the vertical difference between the 'upper' IGS-to-SRAP and 'lower' conventional
 210 final approach profiles, the wake turbulence separation minima can be reduced when Medium
 211 (e.g. Airbus A320) and Light aircraft types are flying on the (upper glide') final approach while
 212 the Heavy and Super category types are assigned to the 'Lower glide' one. The design of the
 213 IGS-to-SRAP wake turbulence separation minima is based on the RECAT-EU methodology
 214 previously endorsed by EASA. However it is intended that a specific safety case will be
 215 introduced to EASA as part of the V4 phase and regulatory acceptance.
- 216 • For operating IGS-to-SRAP, in order to support the more complex separation management
 217 between the traffic on 'lower' and 'upper' glides, the Air Traffic Controllers were supported by
 218 the ORD tool (developed by PJ02-01 in Wave 1). The use of ORD tool was found beneficial from
 219 a safety point of view as reducing the risk of under-spacing.
- 220 • The use of two interception altitudes can enable to take full advantage of the wake separation
 221 reduction (since longitudinal separation can already be reduced before glideslope
 222 interception), however this might introduce higher operational complexity that will need to be
 223 managed by Air Traffic Controllers or with the ORD tool support.

224 Following recommendations from Wave 1, Wave 2 considered the following non-nominal situations,
 225 from the air traffic controllers' side:

- 226 • Sudden loss of the ATC ORD separation tool.
- 227 • Detection by a support tool of a wrong glide slope interception by an aircraft, not intercepting
 228 the expected or cleared slope.
- 229 • Go-arounds/Missed approaches.

230 For each case, the way to manage it was defined in close link with air traffic controllers, then assessed,
 231 through real-time simulation, refined, re-assessed until reaching a solution safe and manageable for
 232 the controllers.

233 5.2 Results from Pilots' side

234 As a general result, almost all of the participating pilots indicated that they can imagine using the
 235 concept of Increased Glide Slope to Second Runway Aiming Point in an every-day operation, and that
 236 they would find it acceptable that ATC consistently puts them on the 2nd threshold during the
 237 approach to the airport, provided the increased slope is manageable by them. Therefore it can be
 238 concluded that the concept is operationally feasible.

239

240 From onboard side, the key changes concern the visual aids, including the PAPI, runway markings and
241 approach lighting system. Different solutions were evaluated through cockpit simulations.

242 In addition, VLD1 project evaluated the two aircraft enablers through flight trials.

243 **5.2.1 Approach lighting system**

244 For the lighting system, two design options were assessed both in Wave 1 and Wave 2 using flight
245 simulation exercise: a steady configuration where both threshold/aiming point and touchdown zone
246 (TDZ) area were permanently illuminated, and a switching configuration where the approach lighting
247 was illuminated for one of the thresholds, depending on which approach was the next landing. The
248 switch took place as soon as the lead aircraft left the TDZ area, in case the next landing aircraft was
249 assigned onto the other final approach slope. Each aiming point was supported by a dedicated PAPI.

250 The results of the tests of Wave 1 and Wave 2 showed that one solution was preferred in certain cases,
251 and the other in other cases. Having that in mind and considering the complexity and the cost of the
252 development of the switching solution, a last set of cockpit simulation was organised with the steady
253 solution only, and with pilots that had never seen the other solution.

254 The final conclusion is that the steady approach lighting is found acceptable and safe in all situations.

255 **5.2.2 Runway marking**

256 In Wave 2, a cockpit simulation was performed to assess different proposals for the runway marking
257 of the second threshold. The conclusion of these simulations was that pilots prefer the duplication of
258 the ICAO marking or the chequered option of the ICAO marking.

259 For the flight tests in Twente, the ICAO duplicated solution was implemented, and the pilots found it
260 acceptable and safe.

261 As a conclusion, both duplication of the ICAO marking and chequered option of the ICAO marking can
262 be used for the second threshold.

263 **5.2.3 PAPI**

264 All the flight simulations performed in Wave 1 and Wave 2 used a PAPI for the first threshold positioned
265 on one side of the runway and one for the second threshold on the other side.

266 The same was implemented for the flight trials performed in Twente.

267 The conclusion of all the tests is that both proposed solutions, red/white or red/green, are acceptable.

268 **5.2.4 Second threshold numbering**

269 In Wave 1 and 2 validation activities including the flight trials, the second threshold number was first
270 one plus one (08 and 09, or 05 and 06).

271 During the flight simulations, discussions took place with pilots about other possible solutions, and the
272 conclusion was that the chosen option was acceptable.

273 5.2.5 Charts

274 For the flight simulations and the flight trials, charts were developed for the IGS-to-SRAP approaches.
 275 They included:

- 276 • For both standard and IGS-to-SRAP procedures, the indication about PAPI location for the
 277 procedure.
- 278 • For IGS-to-SRAP procedure, the indication of the second threshold location, highlighted in red,
 279 and the corresponding vertical profile.

280 5.2.6 On-board assistance to aircraft Energy Management

281 The Energy Management system was tested by the Honeywell flight crew during 23 approaches (plus
 282 final Honeywell flight testing of improved EM prototype¹ was done in US based on results from
 283 Ciampino demo).

284 Overall, the Energy Management system proved to be useful during ISGS procedure, especially during
 285 the approach to an unfamiliar airport in bad weather conditions. With modified EM prototype it was
 286 observed improved crew awareness about timing of configuration changes when performing ISGS
 287 procedures. Nevertheless, prototype needs further improvement to increase level of usability and
 288 effectiveness, how it supports the crew during ISGS procedures. More specifically and based on final
 289 EM flight test results conducted in November 2022 in US following needs for improvements were
 290 identified:

- 291 • Improve drag component of the performance model
- 292 • Harmonize further FMS & Displays messages – timing and content of the messages

293 Maturity status

- 295 - EM on Embraer 170 reached TRL5 and is close to TRL6 (NASA TRL process). After
 296 improvements identified in last flight demonstrations, plan is to have it available on NG FMS²
 297 core with entry to service from 2025-2026.
- 298 - It is expected further expansion to more NG FMS equipped platforms under Honeywell
 299 Primus® Epic (exact aircraft type is not specified yet, however full list of Primus® Epic
 300 equipped aircraft can be found [here](#)).
- 301 - EM on Airbus, if agreed with Airbus and after dedicated re-design per Airbus requirements as
 302 well as adaptation of the Airbus FMS platform, development phase and testing, the EM
 303 function could target an FMS update by ~2030.
- 304 - Boeing – plans still to be defined.

¹ It has to be noted that it was an experimental prototype with known limitation, which still need to be considered during the result interpretation.

² NextGen FMS

305 5.2.7 On-board assistance to Flare

306 The Flare Assistant was implemented on the Honeywell primary flight display (E170 used within
 307 Ciampino demo was not equipped with HUD). Due to safety reasons, pilots did not look at the primary
 308 flight display during the Flare phase of flight. Therefore, the post evaluation video review was
 309 conducted with 2 pilots, who were asked to observe 4 recorded ISGS approaches captured during the
 310 Ciampino trials, where Primary Display with the Flare Assistant was visible.

311 Overall, Pilots' feedback suggest that the Flare Assistant proved to be useful and could effectively
 312 support pilot during ISGS procedures. Nonetheless, the usability of the system needs to be further
 313 improved and especially, in the case where the Flare related cues are provided on the *head-up* instead
 314 of the *head-down* display.

315 Maturity status

- 316 - Given the limitation of not having HUD equipped a/c for flight demo during concerned
 317 demonstration activities, the maturity estimated for this technology is currently within range
 318 of ~TRL4 - TRL5 (or e.g. TRL5 ongoing).
- 319 - Based on the results, *head-down display* (HDD) solution is not preferred. Flare assistant shall
 320 be integrated on *head-up display* (HUD).
- 321 - Next steps with respect to HUD implementation and entry to service still to be defined.

322 5.3 Performance achievements

323 5.3.1 Runway throughput

324 Most of the validation runs from Wave 1 show an increase in throughput as a result of IGS-to-SRAP
 325 and associated wake turbulence separation minima reduction. This can reach up to 7% depending on
 326 the separation scheme used (ICAO, RECAT-EU or RECAT-EU-PWS) and the traffic mix, as smaller aircraft
 327 types (Medium and Lights) are assigned to the approach with the aiming point located downstream
 328 and the larger types (Heavy and Super) are left on the 'lower' approach.

329 5.3.2 Environmental impact

330 SRAP has a positive impact on fuel burn savings as the flight duration is reduced.

331 Regarding the exposure of residents living in immediate vicinity of the airport, there is a reduction of
 332 affected residents since the noise contour location is shifted closer to the airport area.

333 The VLD1-W2 DREAMS Demonstration exercise at Twente (EHTW) airport concludes with noise
 334 reduction due to IGS-to-SRAP with 3.5° glide slope. Aiming for an IGS-to-SRAP threshold further down
 335 the runway displaces the ground noise impact area towards the airport and away from inhabitants and
 336 makes the aircraft noise benefit from the altitude difference. The IGS-to-SRAP procedure with 3.5°
 337 glide slope makes the aircraft noise benefit by increasing the altitude difference. For IGS-to-SRAP
 338 procedures, noise reduction is visible when looking at the LMax levels under-track, and area shift is
 339 visible when reviewing noise contours.

340

341

342 6 Recommendations and Additional 343 activities

344 Flight trials already took place in Wave 2, but only the runway marking and the second PAPI were
345 evaluated.

346 It would be great to have as well the possibility to evaluate in additional live trials, the steady lighting
347 and the impact on the controllers, of the management of IGS-to-SRAP procedures mixed with standard
348 approach procedures. However, due to the cost of the installation of the light for the steady lighting
349 and for the upgrade of controllers HMI to accommodate IGS-to-SRAP, it seems to be very unlikely to
350 be possible as part of new validation activities.

351 Regarding regulation and standardisation, engagement with regulatory bodies, EASA and ICAO should
352 be undertaken to seek the necessary regulatory evolution associated to IGS-to-SRAP visual aid
353 (AMC/GM to Aerodrome regulation EU 139/2014 and ICAO Annex 14) and AMC/GM to Common
354 Requirements regulation EU 2020/469 Part-ATS).

355 Regarding ATS, the IGS-to-SRAP procedure and phraseology should also be subject to the necessary
356 regulatory framework.

357 Besides these aspects, there is also a need to seek for regulatory endorsement of the adaptation of
358 wake turbulence separation minima applicable to IGS-to-SRAP operations. In this view, EUROCONTROL
359 developed a generic safety case to be submitted to EASA (using a similar approach as previously
360 applied for RECAT-EU and TBS wake minima).

361 The VLD1-W2 DREAMS flight trial at Twente led to the following additional recommendations

- 362 • When implementing such solutions in daily operations, it is highly recommended to have both
363 PAPI's operating at equal brightness.
- 364 • In case the IGS-to-SRAP procedures are to be performed in worse weather conditions than the
365 VMC encountered during the tests, the use of (some kind of) IGS-to-SRAP approach lights is
366 recommended.
- 367 • For approaches to runways with conventional and IGS-to-SRAP procedures, it may be good for
368 the mindset to include the runway designation also in the 500 ft call.
- 369 • Small changes/additions to the approach briefing and crosschecks to verify the correct runway
370 end will need to be incorporated in the SOPs.
- 371 • For a good mental picture, it may be helpful to include "lower/higher glide" in traffic info
372 messages.
- 373 • In IGS-to-SRAP charts it may be even more clear when using "2nd Threshold" in the header.
- 374 • If PAPIs are on opposite sides of the runway for first and second threshold, it could be possible
375 and considered to add that information to the phraseology as an additional distinguishing
376 factor.
- 377 • Inclusion of "first/second runway" in the landing clearance is acceptable, whereas the choice
378 of runway designator remains subject of personal preference: some Pilot subjects prefer e.g.
379 "05A/B" over "05/06".

380 Further demonstration activities are recommended to assess the ATC impact and demonstrate the
381 HP and SAFETY feasibility of the proposed solutions before the deployment.

382 **7 Actors impacted by the SESAR Solution**

383 The following actors are impacted by the introduction of IGS-to-SRAP:

- 384 • Air Traffic Controllers;
- 385 • Flight Crews;
- 386 • ANSPs;
- 387 • Regulatory Authorities.

388 **8 Impact on Aircraft System**

389 SRAP has no impact on aircraft system.

390 9 Impact on Ground Systems

391 Impact on the Approach ATC system as it must allow the controller to assign an IGS-to-SRAP approach
392 procedure to a flight when required.

393 Impact on the Tower ATC system as it must allow the controller to distinguish between flights using
394 IGS-to-SRAP approaches and others.

395 Impact on airport infrastructure as the marking and lighting for the second threshold have to be
396 installed, as well as a second PAPI.

397 **10 Regulatory and standardisation**
 398 **Framework Considerations**

399 The following regulatory and standardisation needs are anticipated:

- 400 • Development of corresponding AMC into the Part-ATS of regulation EC. 2017/373 Common
 401 requirements for Air Traffic Management / Air Navigation Service
- 402 ○ based on generic safety cases on the evolution of wake turbulence separation minima
 403 associated to EAP, to be submitted for EASA regulatory approval
- 404 • Proposal for Amendment of the ICAO Document 4444 PANS-ATM
- 405 ○ with the EASA AMC on EAP wake turbulence separation minima
- 406 • Development of requirements for visual aids supporting IGS-to-SRAP and integration into EC.
 407 139/2014 on Aerodromes
- 408 • Proposal to Amendment ICAO Annex 14 with provisions for visual aids, supporting IGS-to-SRAP
 409 based on EASA requirements.

410 11 Solution Data pack

411 The solution Data Pack includes the following documents:

- 412 • D4.5.002 - PJ.02-W2-14.2 SPR-INTEROP/OSED final. Part I of the document contains
413 requirements for the solution.
- 414 • D4.2.008 - PJ.02-W2-14.2 TS/IRS Final. The document contains the technical requirements of
415 the solution.
- 416 • D4.2.006 - PJ.02-W2-14.2 VALR Final. The document contains the results of the validation
417 activities performed in W2 (ATC real time simulation for non-nominal situations and flight
418 simulations)
- 419 • D4.2.010 - PJ.02-W2-14.2 CBA Final. The document is the cost benefit analysis of the
420 solution.

421 In addition, the following document are as well available:

- 422 • VLD1 D1.4 – DEMOR. The document has been developed as part of VLD1-W2 DREAMS and
423 gathers the results of the flight trials performed in that project.
- 424 • PJ02 Wave 1 D2.1.04 - PJ02-02 VALR (Final), Edition 00.01.00, 19 March 2020. This document
425 was developed in PJ02 EARTH project (Wave 1) and gathers the results of the validation
426 activities performed in solution PJ02-02 which was encompassing in particular IGS-to-SRAP.

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