

# PJ.02-W2-14.5 TS IRS

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- 13 Undertaking under conditions.

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17 **AART** 

#### 18 AIRPORT AIRSIDE AND RUNWAY THROUGHPUT

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- 20 This Technical Specification is part of a project that has received funding from the SESAR Joint
- Undertaking under grant agreement No 874477 under European Union's Horizon 2020 research and
   innovation programme.



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23

#### 25 Abstract

This Technical Specification provides the requirements for ground based ATC systems and aircraft systems supporting the solution PJ.02-W2-14.5:

AO – 0331 - Enhanced Arrival procedures using an Increased Glide Slope to a Second Runway
 Aiming Point (A-IGS-to-SRAP)

30 Those requirements were consolidated and refined during the validation exercises.

31





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## **121 1 Executive summary**

- This TS/IRS document provides the architecture and the requirements for SESAR 2020 solution PJ.02 W2-14.5. It will focus on the following change to current capabilities:
- The capability to operate on two runway thresholds permanently published with a higher glide slope towards the second one (IGS-to-SRAP).
- 126 Enhanced Arrival Procedures concepts were already investigated within SESAR 2020 W1 in PJ02-02,

127 but they did not achieve full V3 maturity. Solution PJ.02-W2-14.5 aims then at completing the

validation activities on IGS-to-SRAP concept, so that they can be moved to next phases of validation

129 cycle.

Code	Concept Name	Description	Maturity at PJ02-02 start	Maturity target at PJ02-02 end
AO-0331	Increased Glide Slope to Second Runway Aiming Point (IGS-to- SRAP)		V3 on-going	V3

- Table 1: Initial and targeted maturity level of concepts encompassed by PJ02-02
- 131

132 This document provides requirements for ground based ATC systems and aircraft systems 133 supporting IGS-to-SRAP Procedures. Those requirements are based on the use cases defined in SPR-134 INTEROP/OSED (reference [27]):

- 134 INTEROP/OSED (reference [37]):
- 135 [NOV-5][EAP-03] IGS-to-SRAP Published Approach





# 136 **2 Introduction**

#### 137 **2.1** Purpose of the document

- 138 This TS/IRS document is used to capture and consolidate the set of Technical Requirements related
- to SESAR 2020 W2 solution PJ.02-W2-14.5.
- 140 The requirements included in this TS/IRS satisfy requirements captured at SPR-INTEROP/OSED and
- 141 are associated with Functions, Functional blocks and Roles available in EATMA applicable version.
- 142 TS/IRS aims to provide sufficient information so as to allow the functional block (or parts of it in
- 143 which the project is working) to be designed and implemented either as separate functional block or
- as part of an integrated system, depending upon the design choice, for V&V activity within the
- 145 programme and ultimately for industrialization, standardization and deployment.

## 146 **2.2 Scope**

- 147 Solution PJ.02-W2-14.5 aims at improving airport performances on the Environmental Sustainability
- and Capacity Key Performance Areas by introducing Increased Glide Slope to Second Runway Aiming
- 149 Point Procedures (IGS-to-RAP).
- 150 IGS-to-SRAP procedures/operations allow reducing the environmental impact (e.g. noise, fuel). In
- addition, runway throughput may be increased (e.g. via optimization of wake turbulence
- 152 separations).
- The OI is considered to have reached V3 ongoing maturity level at the end of SESAR 2020 PJ02 W1 and the aim of PJ.02-W2-14.5 is to bring them to V3.
- 155 The following table provides the scope of SESAR solution PJ.02-W2-14.5 and the related OI. The
- description of the procedures associated to the concept is detailed in SPR-INTEROP/OSED
- 157 document [37].

OI Step code	OI Step title	OI Step coverage
AO-0331	Enhanced Arrival Procedure using an	Full
	Increased Glide Slope to a Second Runway	
	Aiming Point (IGS-to-SRAP)	

This enhanced arrival procedure, applying an Increased Glide Slope (above the approach angle in use to the considered runway threshold and up to 4.49°) to an Aiming Point further down the runway threshold (as specified in the published chart), will enable inbound aircraft to reduce noise footprint (environmental benefit) and possibly reduce runway occupancy time and/or taxi-in time depending on local runway/taxiway layout. Unlike the Increased Glide Slope concept (which applies to the runway physical threshold), increasing the glide slope on an additional (second) runway aiming point should prevent a potential reduction of airport capacity and potentially increasing it through optimization in wake turbulence separations. Compared to benefits gained from the Second Runway Aiming Point concept (using the same glide path angle for both glide slopes), increasing the glide slope on the additional (second) runway aiming point allows a potential increase of airport capacity through optimization in wake turbulence separations with a limited / shorter displacement of the additional runway aiming point.

158 159 Table 2: SESAR Solution PJ.02-W2-14.5 Scope and related OI

- 160 This document contains requirements for ground based ATC systems and aircraft systems supporting
- 160 This document contains requirements for ground based ATC systems and aircraft systems supporting 161 IGS-to-SRAP Procedures. Requirements are based on the five use cases defined in SPR-162 INTEROP/OSED (reference [37]):





163 • [NOV-5][EAP-03] IGS-to-SRAP Published Approach

### 164 **2.3 Intended readership**

- 165 The intended audience of this document is initially the partners of Solution PJ.02-W2-14.5 in order
- 166 to support suitable validation exercises.
- 167 Airborne and ground industries are also a primary audience as the TS/IRS allows them to assess the
- 168 impact on airborne systems and ground-based ATC systems of implementing SRAP Procedures.
- 169 Finally this document will support Airspace Users, ANSPs, Airport Operators and Safety Regulators
- 170 willing to develop SRAP procedures.

## 171 **2.4 Background**

- 172 PJ.02-W2-14.5 complements studies carried out in the frame of SESAR 2020 PJ02-02 W1.
- 173 The picture below shows the validation activities performed in PJ02 W1 on IGS-to-SRAP. Details on the
- 174 outputs of these activities can be found in [38].

1/2	FTC	2010
VS	FIS-	2018
		2010

#### P02-02:

- FTS9 Barcelona
- FTS12 Heathrow
- FTS13 Generic airport

## V3 RTS - 2018 and 2019

## P02-02:

- RTS2 CDG
- RTS3 CDG
- RTS5 Munich

- 175 176
- 177
- 178

180

187

#### 179 Figure 1: Validations activities performed on IGS-to-SRAP in SESAR 2020 W1 PJ02-02

- 181 The major recommendations from PJ02-02 were:
- the need to consider the non-nominal situations, and in particular the loss of the ATC tool supporting the controllers in ensuring the needed separations between the aircraft approaching on standard and SRAP procedures
- the need to consider go-arounds/missed approaches
- the need to have a controller alert when an aircraft is not flying the expected glide
  - the need to further evaluate the proposed runway marking and lighting solutions.

### 188 **2.5 Structure of the document**

189 The structure of the document is as follows:

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- 190 Chapter 1: This section introduces the document. • Chapter 2: This section provides the document introduction, its scope, purpose, intended 191 • audience, background information as well as the glossary of terms and acronyms. 192 193 Chapter 3: This section gives a description overview of the SESAR Solution developed in this 194 TS document. Chapter 4: This section provides the Technical Specifications (TS) that have been validated 195 • during validation activities at V3 level. 196 197 Chapter 5: This section describes the options that can be chosen when implementing the • solution. 198 Chapter 6: This section describes any assumptions made that have an impact on the 199 • technical specifications described in section 5. 200 Chapter 7: This section lists the references and applicable documents used in producing this 201 • 202 Chapter 8: This chapter presents the Service Description Document (SDD).
- Chapter 9: This chapter presents the Service Technical Design Document (STDD).

Term	Definition	Source of the definition
Enhanced arrival procedures	Generic term referring in a general manner to all PJ02-02 operational concepts: IGS, A-IGS, SRAP, IGS-to-SRAP, CSPR-ST	ICAO Annex
Obstacle Clearance Altitude/Height (OCA/H)	In a precision approach procedure, the OCA/H is defined as the lowest altitude/height at which a missed approach must be initiated to ensure compliance with the appropriate obstacle clearance design criteria	
Autopilot / Flight Director	AP/FD means that both the Autopilot and the Flight Director are used by the flight crew. They are both driven by the guidance targets coming either from the FMS (FPLN follow up) or the flight crew itself (target selected on Auto Flight system Control Panel). The pilot does not touch the aircraft stick command. FD only means that the Flight Director is displayed and followed manually (using the stick command) by the flight crew on the Primary Flight Display. Without AP/FD means that the flight crew flies a pure manual final approach with the unique aid of lateral and vertical deviations displayed on the Primary Flight Display.	Project proposed definition
Ground Based Augmentation System (GBAS)	Civil-aviation safety-critical system that supports local augmentation of the primary GNSS constellation(s) by providing enhanced levels of service that support all phases of approach (precision and non-precision), landing, departure, surface operations and it may support additional operations: en route and terminal operations. While the main goal of GBAS is to provide integrity assurance, it also increases the accuracy. The technology can be based on GPS L1 providing Cat I, GPS L1 providing up to Cat III, and Multi-Constellation / Multi-Frequency GBAS providing up to Cat III with improved integrity and availability compared to GBAS based on GPS L1 only.	EATMA

#### 204 **2.6 Glossary of terms**





EATMA

	Space	Based	Civil aviation safety-critical systems that support wide-
Augmentation			area or regional augmentation though a monitoring and
System (SBAS)		5)	reference stations network and geostationary (GEO)
			satellites (35.786 km altitude) which broadcast GNSS
	augmentation information (correction & integrity).		

#### 205 Table 3: Glossary

#### 2.7 Acronyms and Terminology 206

Acronym	Definition	
AAL	Above Aerodrome Level	
ACC	Area Control Center	
ADD	Architecture Definition Document	
AFCS	Automatic Flight Control System	
AFS	Automatic Flight System	
AGL	Above Ground Level	
A-IGS	Adaptive Increased Glide Slope	
AMAN	Arrival Manager	
ANP AR	Required Navigation Performance Authorization Required	
AO	Aerodrome Operations	
AODB	Airport Operational Data Base	
AOM	Airspace Organisation and Management	
AOP	Airport Operational Plan	
AP	Auto Pilot	
АРОС	Airport Operations Center	
ASAS	Airborne Separation Assistance System	
A-SMGCS	Advanced Surface Movement Guidance and Control	
	System	
ATC	Air Traffic Control	
ATCO	Air Traffic Controller Operator	
ATFCM	Air Traffic Flow and Capacity Management	
ATIS	Automatic Terminal Information Service	
ATM	Air Traffic Management	
CDI	Course Deviation Indicator	
CDM	Collaborative Decision Making	
CDO	Continuous Descent Operations	
CONOPS	Concept of Operations	
СР	Control Panel	
CSPR-ST	Closely Space Parallel Runway - Staggered Thresholds	
CWP	Controller Working Position	
DA(H)	Decision Altitude/Height	
DCB	Demand and Capacity Balancing	
DMAN	Departure Manager	
DOD	Detailed Operational Description	
DS	Double Slope	
DT	Displaced Threshold	
E-ATMS	European Air Traffic Management System	

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FAF	Final Approach Fix	
FAP	Final Approach Point	
FAS	Final Approach Segment	
FCOM	Flight Crew Operating Manual	
FD	Flight Director	
FMS	Flight Management System	
FPL	Flight Plan	
FRAP	Further Runway Aiming Point	
G/S	Glide Slope	
GAST	GBAS Approach Service Type	
GBAS	Ground-Based Augmentation System	
GLS	GBAS Landing System	
GNSS	Global Navigation Satellite System	
GPA	Glide Path Angle	
HMI	Human Machine Interface	
IFR	Instrument Flight Rules	
IGE	In Ground Effect	
IGS	Increased Glide Slope	
IGS-to-SRAP	Increased Glide Slope to Second Runway Aiming Point	
INTEROP	Interoperability Requirements	
IRS	Interface Requirements Specification	
KPI	Key Performance Indicator	
LNAV	Lateral Navigation	
LOC	Localizer	
LPV	Localizer Performance with Vertical Guidance	
LTS	Lower Than Standard	
LVTO	Low Visibility Take-Off	
MAPt	Missed Approach Point	
NavDB	Navigation Database	
NM	Nautical Mile	
OAT	Outside Air Temperature	
OCA/H	Obstacle Clearance Altitude/Height	
OCD	Operational Concept Description	
OFA	Operational Focus Areas	
OGE	Out-of-Ground Effect	
01	Operational Improvement	
OSED	Operational Service and Environment Definition	
OTS	Other Than Standard	
PAN	Precision Approach Navigator	
PANS	Procedures for Air Navigation Service	
PBN	Performance Based Navigation	
QNH	Barometric pressure adjusted to sea level	
RAVC	Reduced Aerodrome Visibility Conditions	
RAVP	Reduced Aerodrome Visibility Procedures	
RET	Rapid Exit Taxiway	
RF	Radius to Fix	
RMP	Radio Management Panel	
RNP	Required Navigation Performance	

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RPID	Reference Path IDentifier	
SESAR	Single European Sky ATM Research Programme	
SESAR Programme	The programme which defines the Research and Development activities and Projects for the SJU.	
SID	Standard Instrument Departure	
SIS	Signal-in-space	
SJU	SESAR Joint Undertaking (Agency of the European Commission)	
SJU Work Programme	The programme which addresses all activities of the SESAR Joint Undertaking Agency.	
SOP	Standard Operating Procedure	
SPR	Safety and Performance Requirements	
SRAP	Second Runway Aiming Point	
STAR	Standard Terminal Arrival Route	
TAD	Technical Architecture Description	
TBD	To Be Defined	
TBS	Time Based Separations	
ТСН	Threshold Crossing Height	
TIBT	Target In-Block Time	
TLDT	Target Landing Time	
TMA	Terminal Manoeuvring Area	
ToD	Top Of Descent	
TS	Technical Specification	
ТТОТ	Target Take Off Time	
Vapp	Approach Speed	
VDB	VHF Data Broadcast	
VHF	Very High Frequency	
VIS	Visibility	
VNAV	Vertical Navigation	
VPA	Vertical Path Angle	
WTC	Wake Turbulence Category	
WVE	Wake Vortex Encounter	

207 Table 4: Acronyms and terminology





## **3 SESAR Solution Impacts on Architecture**

#### 209 **3.1 Target Solution Architecture**

#### 210 3.1.1 SESAR Solution(s) Overview

PJ.02-W2-14.5: Increased glide slope to a second runway aiming point (IGS-to-SRAP)

211

212 This Solution introduces the Increased Glide Slope to a Second Runway Aiming Point (IGS-to-SRAP)

as a new concept of enhanced approach operation. The distance between the second threshold andthe nominal one is at least of 1100m.

215 IGS-to-SRAP increases runway performance by using two active thresholds on a single runway and

- an increased glide slope to the second one.
- By doing so, the environmental impact (e.g. noise, fuel) should be reduced. In addition, runway
- 218 throughput may be increased (e.g. via optimization of ROT and/or wake turbulence separations).

OI Step		OI description	Open CR
A	0-0331	Enhanced approach operations using an increased glide slope to a second runway aiming point (IGS-to-SRAP)	CR 06476 Update AO-0331 (unlink Institutional EN)
	EN code	EN description	Open CR
	A/C-86	On-board assistance to aircraft energy management	
	A/C-87	On-board assistance to flare	
	AERODRO ME-ATC- 102	Aerodrome ATC system to support final approach operations (distinguish approach procedures)	
	AERODRO ME-ATC- 94	Aerodrome ATC system to support IGS-to-SRAP operations (separation delivery)	
	AIRPORT- 56	Runway marking, lighting and PAPI for SRAP/IGS-to- SRAP approach procedures	
	APP ATC 163	Approach ATC system to support IGS-to-SRAP operations (separation delivery)	
	APP ATC 170	Approach ATC system upgraded to support approach procedure assignment	
HUM-024		Flight Crew new role for handling IGS-to-SRAP approach	





HUM-033	ATC new role for handling IGS-to-SRAP approach	
REG-0533	Regulatory provisions for Increased Glide Slope to Second Runway Aiming Point operations (IGS-to-SRAP)	
STD-112	Update of EASA and ICAO regulatory frameworks for new visual ground aids (SRAP)	

Туре	Element	EN	EN/CR Title	Coverage
		Code		
		AERO	Aerodrome ATC system to support IGS-	to-SRAP
		DROM	operations (separation delivery)	
		E-ATC-		
		94		
		APP	Approach ATC system to support IGS-to	-SRAP
		ATC	operations (separation delivery)	
		163		
		HUM-	Flight Crew new role for handling IGS-to-SRAP	
		024	approach	
		HUM-	ATC new role for handling IGS-to-SRAP approach	
		033		
Role	ATC Executive Controller (PJ.02-W2-14.5)			considered
Role	Tower Runway Controller (PJ.02-W2-14.5)			considered
		REG- 0533	Regulatory provisions for Increased Glid Second Runway Aiming Point operation SRAP)	

220

#### 221 **3.1.1.2** Deviations with respect to the SESAR Solution(s) definition

Enabler	Opt/Req	Deviation
A/C-86_On-board assistance to aircraft energy	Optional	
management		
A/C-87_On-board assistance to flare	Optional	
AERODROME-ATC-102_Aerodrome ATC system	Required	
to support final approach operations (distinguish		
approach procedures)		
AERODROME-ATC-94_Aerodrome ATC system to	Optional	
support IGS-to-SRAP operations (separation		
delivery)		
AIRPORT-56_Runway marking, lighting and PAPI	Required	
for SRAP/IGS-to-SRAP approach procedures		
APP ATC 163_Approach ATC system to support	Optional	
IGS-to-SRAP operations (separation delivery)		
APP ATC 170_Approach ATC system upgraded to	Required	
support approach procedure assignment		
HUM-024_Flight Crew new role for handling IGS-	Required	





to-SRAP approach		
HUM-033_ATC new role for handling IGS-to-SRAP	Required	
approach		
REG-0533_Regulatory provisions for Increased	Required	
Glide Slope to Second Runway Aiming Point		
operations (IGS-to-SRAP)		
STD-112_Update of EASA and ICAO regulatory	Required	
frameworks for new visual ground aids (SRAP)		

#### 3.1.1.3 Relevant Use Cases 223

Operational Use Case		Description
[NOV-5][EAO-03] Published Approach	IGS-to-SRAP	The use case takes place in the execution phase. It describes how one flight performing a published Enhanced Approach Operation (EAO) as an Increased Glide Slope on a Second Runway Aiming Point (IGS-to-SRAP) approach is integrated in a flow of traffic.
		The use case starts when the flight enters the approach control area (taking into account that the Flight Deck has performed a "Prepare & Brief Approach" at the end of cruise), and is initiated following a request from Approach Executive Control and ends when the aircraft has landed.
		<ul> <li>Pre-conditions:</li> <li>The ANSP shall inform Airspace Users (e.g. via AIC) about the availability of IGS-to-SRAP procedure with their differences from the local conventional approaches (including applicable separation minima, location of the second aiming point, landing distance available etc.)The need for displaying to the Controllers the interception points respective for each procedure shall be evaluated as part of the local deployment, such that the visual references are operationally relevant and unambiguously presented without e.g. cluttering on the controller air surveillance display.</li> <li>ANSPs shall reinforce through a request to Aircraft Operators the need for Flight Plans to be complete and correctly filled with aircraft navigation capabilities.</li> <li>A single IGS-to-SRAP procedure type (i.e. one glideslope angle) may be supported by different navigation guidance systems and part of or all the procedures with same glideslope angle may be active at the same time.</li> <li>The IGS-to-SRAP approach chart shall be specific to one final approach path (i.e. angle and touchdown aiming point) and supporting navigation guidance mean, and shall highlight the glide path angle in case it is significantly increased (e.g. more than 3.5°). The position and color of the associated PAPI shall be indicated on the chart.</li> </ul>
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altitude/distance information for the applicable runway aiming point to facilitate Flight Crew procedure check during the approach.

? Procedure design for IGS-to-SRAP operation shall use a glide path angle limited to 4.49°.

? When designing the SRAP local procedure, the location of the second runway aiming point shall provide sufficient landing distance available for all eligible aircraft at that specific airport.

? When designing the IGS-to-SRAP local procedure and the location of the second threshold and aiming point, the current and future taxiway layout of the aerodrome shall be taken into consideration for facilitating runway vacation.

? IGS-to-SRAP procedures shall be published approach procedures flown based on ILS or GLS or RNP APCH with vertical guidance.

? The design of the GLS or RNAV (LPV, LNAV-VNAV) procedures supporting IGS-to-SRAP shall be compliant with ICAO Doc 8168 and shall be validated in accordance with the Instrument Flight Procedure process specified in ICAO Doc 9906.

? Contingency procedures shall be revised as appropriate to accommodate non-nominal modes or degraded modes of operations like the navigation guidance supporting an active procedure is no longer serviceable or the ATC separation support function is no longer serviceable (e.g. loss of separation distance indicator).

? "Approach Supervision shall decide when a published IGS-to-SRAP becomes active/inactive for operations, considering the conditions for application are and remain met:

1. No operational ATC & weather limitations

2. Necessary navigation guidance means are serviceable.

? Approach / Tower Supervisors shall inform the Approach / Tower Controllers about the list of active approach procedures.

? Information about a published IGS-to-SRAP being active to a given runway QFU shall be available to the Flight Crew in order to prepare expected approach briefing (e.g. via ATIS).

? SRAP Approach separation minima shall be specified for each combination of published approach procedure with different glideslopes, taking into account the associated navigation means and corresponding vertical accuracy around the published profile, for

? Leader and follower on same glideslope

? Leader upper glide - follower lower glide

? Leader lower glide - follower upper glide.

? When the second runway threshold is not active (i.e. operating only the conventional threshold), the lightings of





	the secondary runway threshold and aiming point shall be switched off such as to avoid confusing the Flight Crew. ? If the Runway Occupancy Time (ROT) is affected by landing on an active further runway aiming point, this ROT spacing shall be taken into account in the runway separation management (ROT might become the most constraining factor due to changes in separation minima). ? For high density operations supported by Separation Delivery Function with TDIs, when IGS-to-SRAP are flown based on RNP APCH navigation, there is a need for flexibility in final approach axis interception (e.g. using vectoring). In such cases, the ANSP shall request on the charts Flight Crew to inform Approach Controller when aircraft is unable to use FMS guidance for final approach axis interception.
[NOV-5][IGS-to-SRAP-Non-Nominal- 01] Missed Approach (Pilot Initiated) / Go-Around Management	This Use Case describes a non-nomial scenario in which missed approach or go-around procedure is initiated during IGS-to-SRAP approach.
[NOV-5][IGS-to-SRAP-Non-Nominal- 02] Procedure for Glide Alert Management	This Use Case describes a non-nomial scenario in which glide alert is activated during IGS-to-SRAP approach.
[NOV-5][IGS-to-SRAP-Non-Nominal- 03] Loss of TBS-ORD separation indicators	This Use Case describes a non-nomial scenario for the loss of TBS/ORD separation indicators during ISGS approach.

Description
This is the technical Use Case for the IGS-to-SRAP procedure
from an airborne point of view.
This is the technical Use Case for the IGS-to-SRAP procedure
from an ATC point of view.
This is a technical realisation of a non-nomial Use Case for missed approach or go-around management during IGS-to-SRAP approach.
This is a technical realisation of a non-nomial Use Case for missed approach or go-around management during IGS-to-SRAP approach.
This is a technical realisation of a non-nomial Use Case for glide alert management during IGS-to-SRAP approach.
This is a technical realisation of a non-nomial Use Case for loss of TBS/ORD separation indicators during IGS-to-SRAP approach.





#### 227 3.1.1.4 Applicable standards and regulations

Institutional Enabler	Standard

228

## **3.1.2 Capability Configurations required for the SESAR Solution**

Enhanced Arrival Operations		Airport			
сс	Op Env	Capability		Node	Stakeholder
APP ACC	Terminal Airspace;	CTA/CTO	Sequencing; Merging; Routes on nd Transfer; Management; management; management; ration Provision; tions Execution; ice Provision e Management; Information ce Separation	Airspace Organisation; En- Route/Approach ATS;	Civil ATS Approach Service Provider; Military ATS Approach Service Provider;
Civil Aircraft	Airport; En-Route; Terminal Airspace;	Arrival Clearance/Instruction Management; CTA/CTO Optimised Clim Optimised Desce Optimised Take-C Execution; RNP based Operation	Management; b Execution; ent Execution; Off / Landing	Flight Deck;	Civil Business Aviation- Fixed Wing; Civil Business Aviation- Rotorcraft; Civil Scheduled Aviation;
Communication Infrastructure	Airport; En-Route; NET-	Network connectiv aeronautical com the airport			Civil CNS Service Provider;





	Network;			Military CNS
	Terminal Airspace;			Service Provider;
Civil Aircraft	Airport; En-Route; Terminal Airspace;	Optimised Descent Execution; Optimised Take-Off / Landing Execution; PinS Operations Execution; RNP based Operations Execution;	Flight Deck;	Civil Business Aviation- Fixed Wing; Civil Business Aviation- Rotorcraft; Civil Scheduled Aviation;
Navigation Infrastructure Ground Based	Airport; Terminal Airspace;		En- Route/Approach ATS;	Civil CNS Service Provider; Military CNS Service Provider;
Navigation Infrastructure Satellite Based		Positioning/Navigation/Timing of Mobiles (airspace) independent of Ground Navaids;		
TWR	Airport;	Airspace Reservation Management; Arrival Sequencing; Clearance/Instruction Management; Coordination and Transfer; Departure Sequencing; Dynamic Runway Allocation; Integrated Arrival/Departure Sequencing; Minimum Pair Separation Provision; Remote Tower Operations Provision; Spacing Technique Management; Wake Turbulence Separation Provision; Weather-Dependent Separation Provision;	Aerodrome ATS;	Civil ATS Aerodrome Service Provider; Military ATS Aerodrome Service Provider;





# 3.2 Changes imposed by the SESAR Solution on the baseline Architecture

233

	Element	Element name	Impact	Change
Enabler	type			
HUM-033	ATC new ro	le for handling IGS-to-SRAP a	approach	
	Role	ATC Executive Controller	Update	
		(PJ.02-W2-14.5)		
	Role	Tower Runway Controller	Update	
		(PJ.02-W2-14.5)		





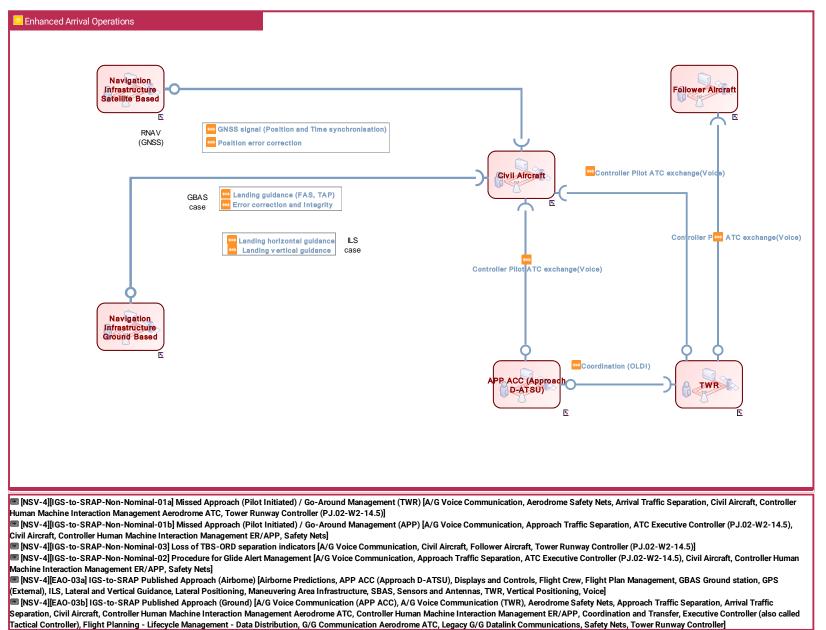
# **4 Technical Specifications**

#### 236 **4.1 Functional architecture overview**

- Functions required to perform needed Operational Activities can be allocated to Resources of a
   different type: Human Role, Infrastructure System or Functional Block.
- 239 4.1.1 Resource Connectivity View
- 240 This view describes the resource connectivity for Solution PJ02-W2-14.5.
- 241 It covers the realization of the following Technical UCs:
- IGS-to-SRAP Published Approach (Airborne)
- IGS-to-SRAP Published Approach (Ground)
- 244
- 245







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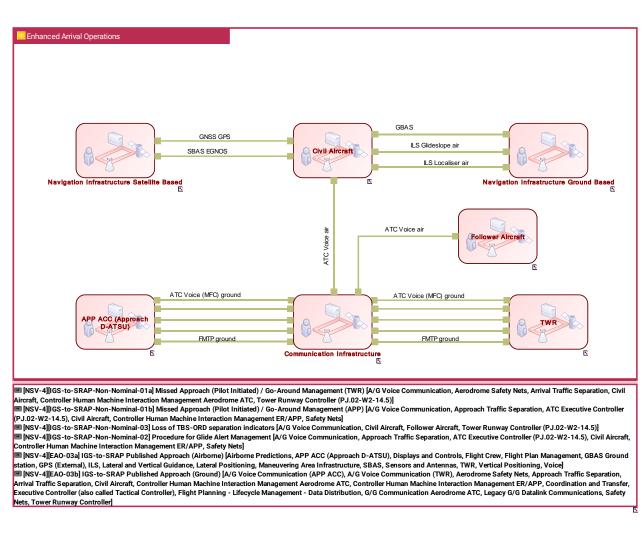


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#### 248 4.1.1.1 Resource Infrastructure View

249

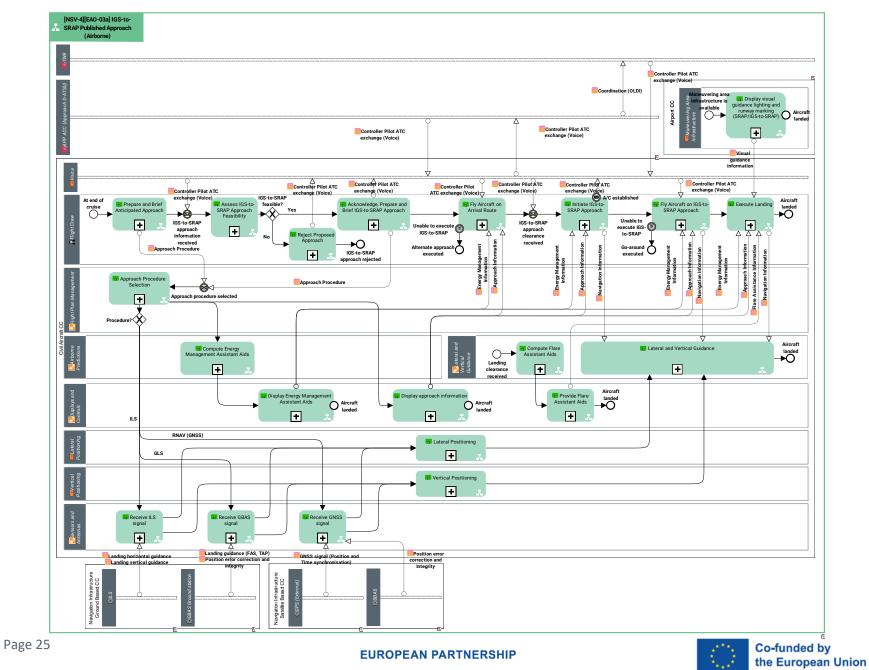


- 252 4.1.1.2 Resource Orchestration View
- 253 4.1.1.2.1 [NSV-4][EAO-03a] IGS-to-SRAP Published Approach (Airborne)
- 254 This is the technical Use Case for the IGS-to-SRAP procedure from an airborne point of view.
- 255

250 251









Role	Functional Block	Function
	Airborne Predictions	Compute Energy Management Assistant Aids;
	Displays and Controls	Display approach information; Display Energy Management Assistant Aids; Provide Flare Assistant Aids;
Flight Crew		Acknowledge, Prepare and Brief IGS- to-SRAPApproach; Approach; AssessAssessIGS-to-SRAPApproach Feasibility; ExecuteExecuteLanding; Fly Aircraft on Arrival Route; Fly Aircraft on IGS-to-SRAP Approach; InitiateInitiateIGS-to-SRAPApproach; Prepare and BriefAnticipated Approach; 
	Flight Plan Management	Approach Procedure Selection;
	Lateral and Vertical Guidance	Compute Flare Assistant Aids; Lateral and Vertical Guidance;
	Lateral Positioning	Lateral Positioning;
	Maneuvering Area Infrastructure	Display visual guidance lighting and runway marking (SRAP/IGS-to-SRAP);
	Sensors and Antennas	Receive GBAS signal; Receive GNSS signal; Receive ILS signal;
	Vertical Positioning	Vertical Positioning;

259

Function

Description





Acknowledge, Prepare and Brief IGS-to-SRAP Approach	Upon proposal of an IGS-to-SRAP procedure by Approach Executive Control, the Flight Deck acknowledges it and immediately initiates the corresponding briefing to prepare the aircraft to fly the IGS-to- SRAP approach procedure, if not anticipated during approach preparation and briefing at the end of cruise.	
Approach Procedure Selection	The aircraft system allows the flight crew to select the approach procedure as performed today for any approach.	
Assess IGS-to-SRAP Approach Feasibility	The Flight Deck assesses the feasibility of the IGS-to-SRAP proposed by ATC, i.e.:	
Approach reasibility	1. Aircraft equipment that is necessary for this procedure is available,	
	2. The proposed published procedure is already available on board,	
	3. The Flight Deck is able to fly such approach	
	4. Meteorological conditions do not prevent the execution of such a procedure	
	The feasibility assessment is considered when receiving the expected approach information and then until the final approach is being flown.	
Compute Energy Management Assistant Aids		
Compute Flare Assistant Aids	The Flare assistant computes an aid considering the state of the aircraft (e.g. weight and landing configuration chosen by flight crew), destination airport information (e.g. final glide slope) and the external environment i.e. destination airfield weather (wind, temperature, pressure).	
Display approach	Approach information are displayed as for any other approach.	
approduti approduti	In case of increased glide slope, function features (e.g. increased	

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information	glide slope value) are displayed in addition the approach information for standard slopes.
Display Energy Management Assistant Aids	Energy management assistant features are displayed in addition the approach information for standard slopes.
Display visual guidance lighting and runway marking (SRAP/IGS-to-SRAP)	That function corresponds to the ground infrastructure necessary to support pilots when landing on a second threshold. That includes the runway marking, the lighting and the PAPI.
Execute Landing	The Flight Deck flies the visual segment after DH (if any) and safely executes landing on the runway.
Fly Aircraft on Arrival Route	The Flight Deck follows arrival procedure or ATC instructions towards the final approach.
Fly Aircraft on IGS-to-SRAP Approach	The Flight Deck flies and monitors the lateral and vertical approach trajectory until reaching the decision height (DH). If distance/altitude information is provided on the chart, it can be used to perform distance/altitude checks.
	The Flight Deck continues managing aircraft energy and configuration following SOP to prepare aircraft for landing, while respecting potential ATC speed instructions as long as they are compatible with stabilization criteria.
	Meanwhile, the Flight Deck contacts Tower Runway Control when instructed to do so in order to receive landing clearance. When visual contact is established with the runway (at or before DH), the Flight Deck needs to properly identify visual references.
Initiate IGS-to-SRAP Approach	Once the IGS-to-SRAP approach clearance has been received, the Flight Deck manages aircraft navigation as appropriate to capture the final approach lateral and vertical path.
	The Flight Deck also manages aircraft energy and configuration following SOP, while respecting procedure altitude and speed constraints, or ATC speed instructions if any.
	Once the aircraft is established on the final approach lateral and





	vertical path, the Flight Deck reports to ATC.
Lateral and Vertical Guidance	Flight Control i.e. the control of the aircraft on its lateral and vertical axis (e.g. Autopilot, Flight Director, Head up display)
Lateral Positioning	Elaboration of A/C latitude and longitude based on external means (GNSS, Radio Navigation, TACAN for Mil A/C) or autonomous means (Inertial Reference System).
	The Flight Deck performs the following sub-tasks:
Prepare and Brief Anticipated Approach	1. obtain weather and landing information for destination and alternate airports
	2. check current aircraft approach and landing capabilities against available airport means and weather conditions
	3. insert expected arrival and approach procedures into the flight plan and check them against published charts
	4. insert relevant performance parameters for approach
	5. insert landing minimum
	6. check/edit relevant performance parameters for go-around
	7. check/perform tuning of relevant NAVAIDs
	8. perform approach briefing
	If the airport operates an Enhanced Arrival Procedure (EAP) approach, the Flight Deck also briefs the most likely EAP procedure.
Provide Flare Assistant Aids for Flare assistant features are provided to the crew (e.)	
Receive GBAS signal	(self-explanatory)
Receive GNSS signal	(self-explanatory)
	(self-explanatory)



Receive ILS signal	
Reject Proposed Approach	Once the proposed approach has been assessed as "not feasible", the Flight Deck rejects it (possibly providing the reason why).
Vertical Positioning	Elaboration of A/C vertical position (altitude, height) based on external means (GNSS) or autonomous means (Baro-Altitude, Radio-Altitude measurements)

#### 261 4.1.1.2.2 [NSV-4][EAO-03b] IGS-to-SRAP Published Approach (Ground)

#### 262 This is the technical Use Case for the IGS-to-SRAP procedure from an ATC point of view.

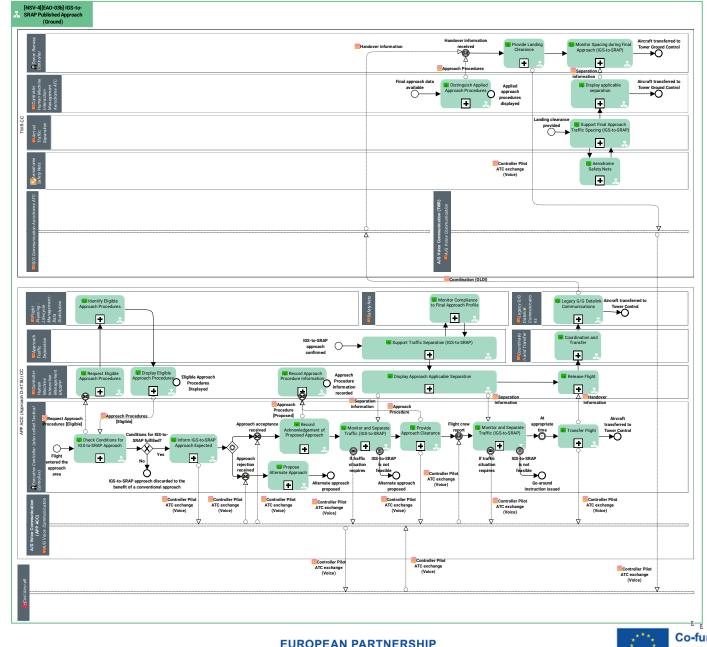
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Role	Functional Block	Function
	Aerodrome Safety Nets	Aerodrome Safety Nets;
	Approach Traffic Separation	Support Traffic Separation (IGS-to- SRAP);
	Arrival Traffic Separation	Support Final Approach Traffic Spacing (IGS-to-SRAP);
	Controller Human Machine Interaction Management Aerodrome ATC	Display applicable separation; Distinguish Applied Approach Procedures;
	Controller Human Machine Interaction Management ER/APP	Display Approach Applicable Separation; Display Eligible Approach Procedures; Record Approach Procedure Information; Release Flight; Request Eligible Approach Procedures;
	Coordination and Transfer	Coordination and Transfer
Executive Controller (also called Tactical Controller)		Check Conditions for IGS-to-SRAP Approach; Inform IGS-to-SRAP Approach Expected; Monitor and Separate Traffic (IGS-to- SRAP); Propose Alternate Approach; Provide Approach Clearance; Record Acknowledgement of Proposed Approach; Transfer Flight;
	Flight Planning - Lifecycle Management - Data	Identify Eligible Approach Procedures;
	Distribution	





	Communications	Communications;
	Safety Nets	Monitor Compliance to Final Approach Profile;
Tower Runway Controller		Monitor Spacing during Final Approach (IGS-to-SRAP); Provide Landing Clearance;

-	
Function	Description
Aerodrome Safety Nets	This functional block detects potential conflicts between two objects (i.e. aircraft or vehicles), or between an object and a restricted area, by processing the actual traffic situation, and triggers alerts within manoeuvring areas (runway/s and taxiways). It is also extended on final approach and take-off path. The potential safety hazards situations on the airport movement area: runway incursion, intrusion in protected areas, aircraft/aircraft and aircraft/vehicle collisions.
Check Conditions for IGS-to- SRAP Approach	Approach Executive Control determines whether a flight can be given an active IGS-to-SRAP published procedure based on:
	? aircraft declared navigation capabilities (assuming flight crew ability),
	? relevance of such a procedure for this flight in current traffic context (density, spacing management, etc.)
Coordination and Transfer	The Coordination & Transfer functional block comprises the management of coordination and transfer of flights between "internal" sectors and with external ATSUs, civil/military coordination, pre-departure clearance coordination, and the processing of oceanic clearances.
	The type of connection with the coordination partner (e.g. internal sector, OLDI ATSU, Flight Object ATSU) is largely transparent to the Coordination and Transfer functional block as the coordination and transfer process is common to all.
	C&T addresses the following aspects:
	? Identification of the sectors/units that are interested in the flight (i.e. that will either control the flight or for which part or all of

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	the flight needs to be coordinated or informed) based on the airspace intersections, as provided by TP&M, together with other data such as flight category (GAT/OAT), rules (IFV/VFR), ADEP/ADES, distance flown in the sector, etc
	? Synchronization of the transfer of frequency with ACM when needed
	? Synchronisation of the SSR code with the upstream centre (in conjunction with GGDC)
	? Identification of LOAs to be used
	? Check that coordinated entry/exit conditions are achievable (e.g. from planned trajectory) and generate consequent warnings
	? Identification of the executive data at the transfer time (i.e. CFL, Assigned ROCD, Assigned Heading?)
Display applicable separation	That function displays the separation delivery indicators linked to each pair of aircraft to help the controller respect the necessary separations between aircraft and optimize the distance between 2 aircraft.
Display Approach Applicable Separation	That function displays the separation delivery indicators linked to each pair of aircraft to help the controller respect the necessary separations between aircraft and optimize the distance between 2 aircraft.
Display Eligible Approach Procedures	That function displays to Executive Controller, on his/her request, the list of active published procedures an aircraft can fly, according to its known capabilities (from flight plan).
Distinguish Applied Approach Procedures	That function displays, on Runway Tower Controller interface, the list of arriving aircraft in such a way that the controller can easily identify which procedure an aircraft is flying. According to the case, that enables the controller to discriminate aircraft going to one threshold or the other (for SRAP and IGS-to-SRAP), flying one slope or the other (IGS, A-IGS), going to one runway or the other (CSPR-ST).
Identify Eligible Approach	That function calculates the list of active procedures an aircraft can fly, according to its known capabilities (from flight plan).





Procedures	
Inform IGS-to-SRAP Approach Expected	Approach Executive Control initiates the IGS-to-SRAP procedure informing the Flight Deck of the expected enhanced arrival approach.
Legacy G/G Datalink Communications	The Legacy Ground-Ground Datalink Communications functional block provides the functionality processing to exchange flight and environment data with the CFMU (IFPS and ETFMS), aircraft operators, other civil and military ATS Units, Air Defence units and Aerodrome system (Departure Management). The functional block translates data between internal interfaces and the standard protocols in use with the external systems (e.g. ICAO, ADEXP, OLDI).
Monitor and Separate Traffic (IGS-to-SRAP)	Approach Executive Control sequences and merges the arrival traffic while respecting all separation and spacing criteria for IGS-to-SRAP procedure using speed and vectoring (altitude and heading) instructions whenever needed.
Monitor Compliance to Final Approach Profile	This Function monitors compliance to the final approach profile, i.e. interception of the right glide path and adherence to the correct glide path.
	Tower Runway Control monitors the final approach, especially:
Monitor Spacing during Final Approach (IGS-to-SRAP)	1. the spacing with aircraft ahead, and
	2. the adherence to the final approach altitude scheme.
	A go-around procedure may be initiated if the conditions for a safe landing are not fulfilled.
	Once the aircraft has landed and vacated the runway, Tower Runway Control transfers the flight to Tower Ground Control.
Propose Alternate Approach	After the Flight Deck has rejected the proposed active EAP, Approach Executive Control takes this refusal into account and clears the arrival flight for another active approach.
Provide Approach Clearance	Approach Executive Control issues, at the appropriate time, and records the approach clearance corresponding to the published chart.





Provide Landing Clearance	At the appropriate time, the tower controller provides the landing clearance as well as the wind information while ensuring that the runway is clear of traffic.
Record Acknowledgement of Proposed Approach	Once the Flight Deck has accepted the proposed approach, Approach Executive Control records the corresponding arrival approach for this particular flight.
Record Approach Procedure Information	This function enables the controller to input and record the approach procedure information.
Release Flight	This function allows the controller to trigger the procedure to release the flight and transfer it to another ATS unit.
Request Eligible Approach Procedures	That function allows the Executive Controller to request to the system the list of active procedures an aircraft can fly.
Support Final Approach Traffic Spacing (IGS-to-SRAP)	This function will support the controller in the delivery of the separation (on final approach) to apply between each pair of aircraft (one of them following an IGS-to-SRAP procedure).
Support Traffic Separation (IGS-to-SRAP)	This function will support the controller in the visualization of the separation to apply between each pair of aircraft (one of them following an IGS-to-SRAP procedure).
Transfer Flight	<ul> <li>At the appropriate time, Approach Executive Control:</li> <li>1. hands over and transfers the control of the flight to Tower Runway Control, mentioning the followed published approach chart, and</li> <li>2. instructs the Flight Deck to contact Tower Runway Control.</li> </ul>

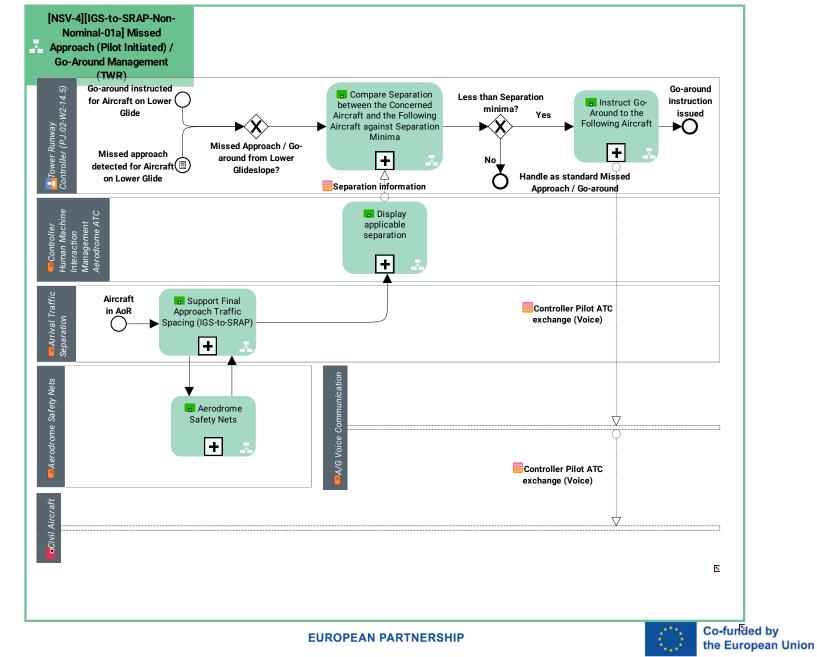
# 4.1.1.2.3 [NSV-4][IGS-to-SRAP-Non-Nominal-01a] Missed Approach (Pilot Initiated) / Go Around Management (TWR)

This is a technical realisation of a non-nominal Use Case for missed approach or go-around management during IGS-to-SRAP approach.

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Role	Functional Block	Function
	Aerodrome Safety Nets	Aerodrome Safety Nets;
	Arrival Traffic Separation	Support Final Approach Traffic Spacing (IGS-to-SRAP);
	Controller Human Machine Interaction Management Aerodrome ATC	Display applicable separation;
Tower Runway Controller (PJ.02-W2-14.5)		Compare Separation between the Concerned Aircraft and the Following Aircraft against Separation Minima; Instruct Go-Around to the Following Aircraft;

Function	Description	
Aerodrome Safety Nets	This functional block detects and triggers alerts within manoeuvering areas (runway/s and taxiways) potential conflicts between two objects (i.e. aircraft or vehicles), or between an object and a restricted area, by processing the actual traffic situation. It is also extended on final approach and take-off path. The potential safety hazards situations on the airport movement area: runway incursion, intrusion in protected areas, aircraft/aircraft and aircraft/vehicle collisions.	
Compare Separation between the Concerned Aircraft and the Following Aircraft against Separation Minima	Executive controller or tower runway controller compares the separation between the aircraft going around and the following one against the separation minima to be applied at the airport.	
Display applicable separation	That function displays the separation delivery indicators linked to each pair of aircraft to help the controller respect the necessary separations between aircraft and optimize the distance between 2 aircraft.	
Instruct Go-Around to the	Executive controller or tower runway controller instructs a go-around to the aircraft following the one already going-around.	





Following Aircraft	
	This function will support the controller in the delivery of the separation (on final approach) to apply between each pair of aircraft (one of them following an IGS-to-SRAP procedure).

# 4.1.1.2.4 [NSV-4][IGS-to-SRAP-Non-Nominal-01b] Missed Approach (Pilot Initiated) / Go Around Management (APP)

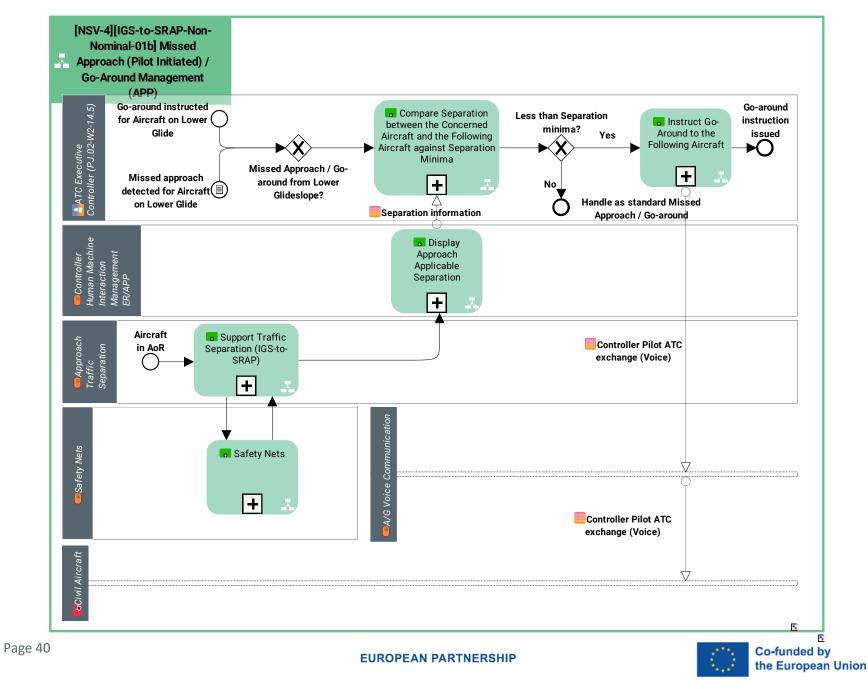
This is a technical realisation of a non-nominal Use Case for missed approach or go-around management during IGS-to-SRAP approach.

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Role	Functional Block	Function
	Approach Traffic Separation	Support Traffic Separation (IGS-to-SRAP);
ATC Executive Controller (PJ.02-W2-14.5)		Compare Separation between the Concerned Aircraft and the Following Aircraft against Separation Minima; Instruct Go-Around to the Following Aircraft;
	Controller Human Machine Interaction Management ER/APP	Display Approach Applicable Separation;
	Safety Nets	Safety Nets;

Function	Description
Compare Separation between the Concerned Aircraft and the Following Aircraft against Separation Minima	Executive controller or tower runway controller compares the separation between the aircraft going around and the following one against the separation minima to be applied at the airport.
Display Approach Applicable Separation	That function displays the separation delivery indicators linked to each pair of aircraft to help the controller respect the necessary separations between aircraft and optimize the distance between 2 aircraft.
Instruct Go-Around to the Following Aircraft	Executive controller or tower runway controller instructs a go-around to the aircraft following the one already going-around.
Safety Nets	The Safety Nets functional block alerts the ATC controllers in case of short-term danger for an aircraft to infringe separation criteria with other aircraft or danger areas or in case the aircraft deviates from the nominal approach path.
	The safety nets functional block encompass the following sub- functions:
	? Short Term Conflict Alert (STCA) detecting and alerting in case of infringement of separation minima between aircraft.





	? Minimum Safe Altitude Warning (MSAW) detecting and alerting in case of infringement the minimum safe altitude form the ground or from an obstacle.	
	? Airspace Proximity Warning (APW) detecting and alerting in case an aircraft is going to infringe restricted airspace.	
	? Approach Path Monitoring (APM) detecting and alerting in case an aircraft deviates from the glide path.	
Support Traffic Separation (IGS-to-SRAP)	This function will support the controller in the visualization of the separation to apply between each pair of aircraft (one of them following an IGS-to-SRAP procedure).	

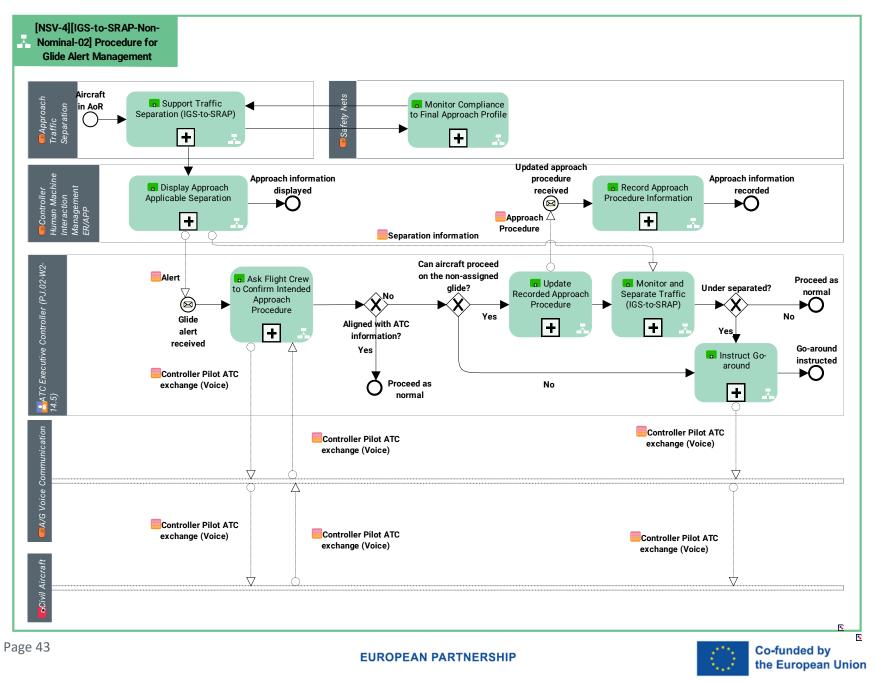
# 290 4.1.1.2.5 [NSV-4][IGS-to-SRAP-Non-Nominal-02] Procedure for Glide Alert Management

This is a technical realisation of a non-nominal Use Case for glide alert management during IGS-to-SRAPapproach.

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Role	Functional Block	Function
	Approach Traffic Separation	Support Traffic Separation (IGS-to-SRAP);
ATC Frequetive Controller		Ask Flight Crew to Confirm Intended
ATC Executive Controller		Approach Procedure;
(PJ.02-W2-14.5)		Instruct Go-around;
		Monitor and Separate Traffic (IGS-to- SRAP);
		Update Recorded Approach
		Procedure;
	Controller Human Machine Interaction Management	Display Approach Applicable Separation;
	ER/APP	Record Approach Procedure Information;
	Safety Nets	Monitor Compliance to Final
		Approach Profile;

Function	Description
Ask Flight Crew to Confirm Intended Approach Procedure	ATC executive controller asks flight crew to confirm they are flying the intended approach procedure.
Display Approach Applicable Separation	That function displays the separation delivery indicators linked to each pair of aircraft to help the controller respect the necessary separations between aircraft and optimize the distance between 2 aircraft.
Instruct Go-around	Executive controller or Tower Runway Controller instructs a go- around to the aircraft that triggered the glide alert or to any heavy aircraft flying on the upper glide (SRAP one).
Monitor and Separate Traffic (IGS-to-SRAP)	Approach Executive Control sequences and merges the arrival traffic while respecting all separation and spacing criteria for IGS-to-SRAP procedure using speed and vectoring (altitude and heading) instructions whenever needed.





Monitor Compliance to Final Approach Profile	This Function monitors compliance to the final approach profile, i.e. interception of the right glide path and adherence to the correct glide path.
Record Approach Procedure Information	This function enables the controller to input and record the approach procedure information.
Support Traffic Separation (IGS-to-SRAP)	This function will support the controller in the visualization of the separation to apply between each pair of aircraft (one of them following an IGS-to-SRAP procedure).
Update Recorded Approach Procedure	This function allows the controller to update the approach procedure information that had been recorded and to record the new one.

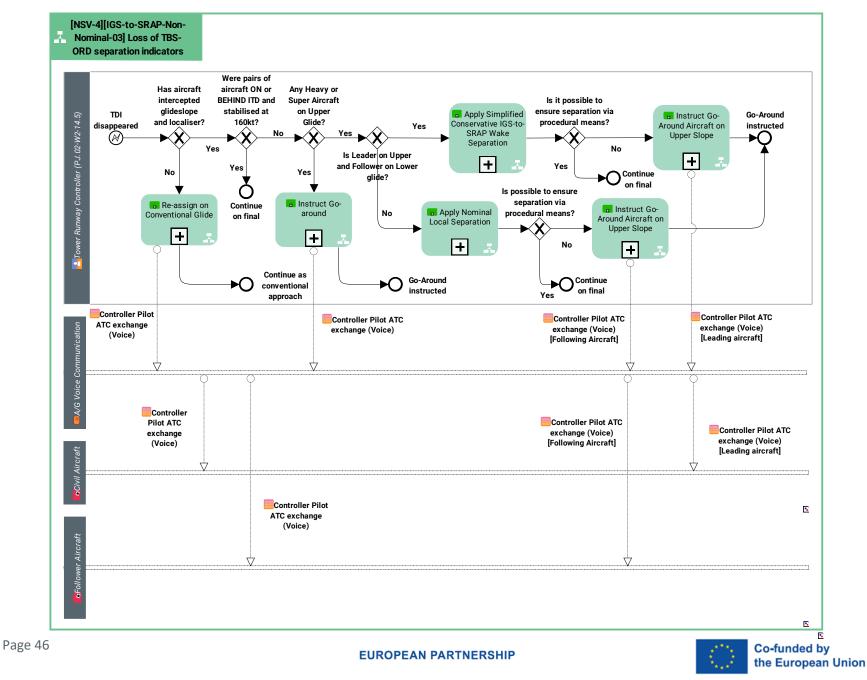
# 299 4.1.1.2.6 [NSV-4][IGS-to-SRAP-Non-Nominal-03] Loss of TBS-ORD separation indicators

This is a technical realisation of a non-nomial Use Case for loss of TBS/ORD separation indicators duringIGS-to-SRAP approach.

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Role	Functional Block	Function
Tower Runway Controller (PJ.02-W2-14.5)		Apply Nominal Local Separation; Apply Simplified Conservative IGS-to- SRAP Wake Separation; Instruct Go-around; Instruct Go-Around Aircraft on Upper Slope; Instruct Go-Around Aircraft on Upper Slope; Re-assign on Conventional Glide;

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Function	Description
Apply Nominal Local Separation	Executive controller or Tower Runway controller applies the nominal wake separations in use at the airport.
Apply Simplified Conservative IGS-to-SRAP Wake Separation	In case of leader on upper glide and follower on lower glide, the separation has to be increased. To simplify the rule as the assistance tool is lost, a simplified conservative wake separation compliant with IGS-to-SRAP is applied by the ATCO, determined at each airport level, according to the separation used locally.
Instruct Go-around	Executive controller or Tower Runway Controller instructs a go- around to the aircraft that triggered the glide alert or to any heavy aircraft flying on the upper glide (SRAP one).
Instruct Go-Around Aircraft on Upper Slope	When necessary separation cannot be ensured, Executive controller or Tower Runway Controller instructs a go-around to the aircraft flying on the upper glide (SRAP one).
Re-assign on Conventional Glide	When separation indicators disappear, Executive controller reassigns to the conventional glide, all aircraft expected to fly a SRAP procedure or already cleared to it, that have not yet intercepted the glide.

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# 309 **4.1.2 Resource Composition**

310 **4.1.3 Service view** 

Service

## 311 **4.1.3.1 Service description**

- 312

Service description

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# 314 **4.1.3.2 Service Provisioning**

Interaction	Consumer CC	Consumer System	Provider CC	Provider System
Controller Pilot ATC exchange(Voice).	Follower Aircraft	Aircraft;	TWR	Voice;
1 Landing horizontal guidance.Civil Aircraft (PJ.02- 02)_CC and Navigation Infrastructure Ground Based_CC (Duplicata)	Civil Aircraft	Aircraft;	Navigation Infrastructure Ground Based	ILS;
1 Landing vertical guidance.Civil Aircraft (PJ.02- 02)_CC and Navigation Infrastructure Ground Based_CC (Duplicata)	Civil Aircraft	Aircraft;	Navigation Infrastructure Ground Based	ILS;
1 Error correction and Integrity.Civil Aircraft (PJ.02- 02)_CC and Navigation Infrastructure Ground Based_CC (Duplicata)	Civil Aircraft	Aircraft;	Navigation Infrastructure Ground Based	GBAS Ground station;
1 Coordination (OLDI).TWR_CC and APP ACC (Approach D-ATSU)_CC (Duplicata)	TWR	Aerodrome ATC;	APP ACC (Approach D-ATSU)	En-Route / Approach ATC;





Interaction	Consumer CC	Consumer System	Provider CC	Provider System
1 Controller Pilot ATC exchange(Voice).Civ il Aircraft (PJ.02- 02)_CC and TWR_CC (Duplicata)	Civil Aircraft	Aircraft;	TWR	Voice;
1 Controller Pilot ATC exchange(Voice).Civ il Aircraft (PJ.02- 02)_CC and APP ACC (Approach D- ATSU)_CC (Duplicata)	Civil Aircraft	Aircraft;	APP ACC (Approach D-ATSU)	Voice;
1 Position error correction.Civil Aircraft (PJ.02- 02)_CC and Navigation Infrastructure Satellite Based_CC (Duplicata)	Civil Aircraft	Aircraft;	Navigation Infrastructure Satellite Based	SBAS;
1 GNSS signal (Position and Time synchronisation).Civ il Aircraft (PJ.02- 02)_CC and Navigation Infrastructure Satellite Based_CC (Duplicata)	Civil Aircraft	Aircraft;	Navigation Infrastructure Satellite Based	GPS (External); GALILEO (External); GLONASS (External); BEIDOU (External);
1 Landing guidance (FAS, TAP).Civil Aircraft (PJ.02- 02)_CC and Navigation Infrastructure Ground Based_CC (Duplicata)	Civil Aircraft	Aircraft;	Navigation Infrastructure Ground Based	GBAS Ground station;

317





## 319 4.1.3.3 Service Realization

# 320 4.1.3.3.1 Interaction 1 Controller Pilot ATC exchange(Voice).Civil Aircraft (PJ.02-02)\_CC

# 321 and APP ACC (Approach D-ATSU)\_CC (Duplicata)

# 322 System Port: ATC\_VOICE\_MFC\_GND at APP ACC\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

323

## 324 **System Port:** VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2
ATC Voice (QSIG) ground	
	ATS QSIG
ATC Voice (VoIP, control) ground	
	SIP
	ТСР
	IP
ATC Voice (VoIP, media) ground	
	RTP
	UDP
	IP
OPC (Operational) Voice ground	

325

## 326 **System Port:** VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2
ATC Voice (QSIG) ground	
	ATS QSIG





ATC Voice (VoIP, control) ground	
	SIP
	ТСР
	IP
ATC Voice (VoIP, media) ground	
	RTP
	UDP
	IP
OPC (Operational) Voice ground	

# 328 **System Port:** ATC\_VOICE\_MFC\_GND at APP ACC\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

# 329

# 330 **System Port:** VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Desta ad Charl	Burtoud	
Protocol Stack	Protocol	
ATC Voice (MFC) ground		
	ATS MFC R2	
ATC Voice (QSIG) ground		
	ATS QSIG	
ATC Voice (VoIP, control) ground		
ATC VOICe (VOIP, CONTION) ground		
	SIP	
	ТСР	
	IP	
ATC Voice (VoIP, media) ground		
	RTP	
	UDP	
	IP	
OBC (Operational) Visica ground		
OPC (Operational) Voice ground		





# 332 System Port: ATC\_VOICE\_MFC\_GND at APP ACC\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

#### 333

## 334 System Port: VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2
ATC Maine (OSIC) around	
ATC Voice (QSIG) ground	
	ATS QSIG
ATC Voice (VoIP, control) ground	
	SIP
	TCP
	IP
ATC Voice (VoIP, media) ground	
	RTP
	UDP
	IP
OPC (Operational) Voice ground	

# 335

# 336 System Port: ATC\_VOICE\_MFC\_GND at APP ACC\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

# 337

## 338 **System Port:** ATC\_VOICE at Civil Aircraft\_CC

Protocol Stack	Protocol
ATC Voice air	
	VHF - AM 25kHz/8.33kHz





|--|

## 340 **System Port:** VOICE\_RADIO\_AIR at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice air	
	VHF - AM 25kHz/8.33kHz
	HF - AM 25kHz

341

# 4.1.3.3.2 Interaction 1 Controller Pilot ATC exchange(Voice).Civil Aircraft (PJ.02-02)\_CC and TWR\_CC (Duplicata)

## 344 **System Port:** ATC\_VOICE\_MFC\_GND at TWR\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

## 345

#### 346 **System Port:** VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2
ATC Voice (QSIG) ground	
	ATS QSIG
ATC Voice (VoIP, control) ground	
	SIP
	TCP
	IP
ATC Voice (VoIP, media) ground	
	RTP
	UDP
	IP
OPC (Operational) Voice ground	

347

348 System Port: ATC\_VOICE\_MFC\_GND at TWR\_CC





Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

350 System Port: VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol	
ATC Voice (MFC) ground		
	ATS MFC R2	
ATC Voice (QSIG) ground		
, the verse (dere) ground		
	ATS QSIG	
ATC Voice (VoIP, control) ground		
	SIP	
	ТСР	
	IP	
ATC Voice (VoIP, media) ground		
	RTP	
	UDP	
	IP	
OPC (Operational) Voice ground		

# 351

# 352 **System Port:** ATC\_VOICE\_MFC\_GND at TWR\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

353

# 354 System Port: VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2
ATC Voice (QSIG) ground	





ATS QSIG
SIP
ТСР
IP
RTP
UDP
IP

## 356 System Port: ATC\_VOICE\_MFC\_GND at TWR\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

# 357

# 358 **System Port:** VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2
ATC Voice (QSIG) ground	
	ATS QSIG
ATC Voice (VoIP, control) ground	
	SIP
	ТСР
	IP
ATC Voice (VoIP, media) ground	
	RTP
	UDP
	IP





OPC (Operational) Voice ground	

# 360 System Port: ATC\_VOICE at Civil Aircraft\_CC

Protocol Stack	Protocol
ATC Voice air	
	VHF - AM 25kHz/8.33kHz
	HF - AM 25kHz

#### 361

## 362 **System Port:** VOICE\_RADIO\_AIR at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice air	
	VHF - AM 25kHz/8.33kHz
	HF - AM 25kHz

363

# 4.1.3.3.3 Interaction 1 Coordination (OLDI).TWR\_CC and APP ACC (Approach D-ATSU)\_CC (Duplicata)

## 366 **System Port:** IP\_GND at Communication Infrastructure (PJ.02-02)\_CC

Protocol

367

## 368 **System Port:** ATS\_COORD\_GND at APP ACC (PJ.02-02)\_CC

Protocol Stack	Protocol
FMTP ground	
	FMTP
	ТСР
	IP

369

#### 370 System Port: ATS\_COORD\_GND at TWR (PJ.02-02)\_CC

Protocol Stack	Protocol
FMTP ground	
	FMTP
	ТСР
	IP





## 372 **System Port:** IP\_GND at Communication Infrastructure (PJ.02-02)\_CC

Protocol Stack	Protocol
IP	

373

# 4.1.3.3.4 Interaction 1 Error correction and Integrity.Civil Aircraft (PJ.02-02)\_CC and Navigation Infrastructure Ground Based\_CC (Duplicata)

## **System Port:** NAV\_GBAS\_AIR at Navigation Infrastructure Ground Based\_CC

Protocol Stack	Protocol
GBAS	
	VDB Link VHF 108 - 117.95 MHz

## 377

## 378 **System Port:** GBAS\_VDB at Civil Aircraft\_CC

Protocol Stack	Protocol
GBAS	
	VDB Link VHF 108 - 117.95 MHz

379

# 4.1.3.3.5 Interaction 1 GNSS signal (Position and Time synchronisation).Civil Aircraft (PJ.02-02)\_CC and Navigation Infrastructure Satellite Based\_CC (Duplicata)

## 382 System Port: SAT GNSS at Civil Aircraft CC

Protocol Stack	Protocol
GNSS GPS	
	L1 1575.42MHz
	L2 1227.6 MHz
	L5 1176.45 MHz

383

**System Port:** NAV\_SAT\_GNSS at Navigation Infrastructure Satellite Based\_CC

Protocol Stack	Protocol
GNSS BEIDOU	
	B1 1561.098 MHz
	B2 1207.147 MHz
	B3 1268.52 MHz





GNSS GALILEO	
	E1 1575.42 MHz
	E5a 1176.45 MHz
	E5b 1207.14 MHz
	E6 1278.75 MHz
GNSS GLONASS	
	L1 1598.0625 - 1605.375 MHz
	L2 1242.9375 - 1248.625 MHz
	L3 1201 MHz
GNSS GPS	
	L1 1575.42MHz
	L2 1227.6 MHz
	L5 1176.45 MHz
SBAS EGNOS	
	L1 1572.42MHz

# 4.1.3.3.6 Interaction 1 Landing guidance (FAS, TAP).Civil Aircraft (PJ.02-02)\_CC and Navigation Infrastructure Ground Based\_CC (Duplicata)

## 388 System Port: NAV\_GBAS\_AIR at Navigation Infrastructure Ground Based\_CC

Protocol Stack	Protocol
GBAS	
	VDB Link VHF 108 - 117.95 MHz

389

## 390 System Port: GBAS\_VDB at Civil Aircraft\_CC

Protocol Stack	Protocol
GBAS	
	VDB Link VHF 108 - 117.95 MHz

391

# 4.1.3.3.7 Interaction 1 Landing horizontal guidance.Civil Aircraft (PJ.02-02)\_CC and Navigation Infrastructure Ground Based\_CC (Duplicata)

394 System Port: ILS\_LOC at Civil Aircraft\_CC

Protocol Stack Protocol
-------------------------





ILS Localiser air	
	UHF 108 - 112 MHz

## System Port: NAV\_ILS\_LOC\_AIR at Navigation Infrastructure Ground Based\_CC

Protocol Stack	Protocol
ILS Localiser air	
	UHF 108 - 112 MHz

397

# 3984.1.3.3.8Interaction 1 Landing vertical guidance.Civil Aircraft (PJ.02-02)\_CC and399Navigation Infrastructure Ground Based\_CC (Duplicata)

## 400 **System Port:** ILS\_GP at Civil Aircraft\_CC

Protocol Stack	Protocol
ILS Glideslope air	
	UHF 328.6 - 335.4 MHz

# 401

# 402 **System Port:** NAV\_ILS\_GP\_AIR at Navigation Infrastructure Ground Based\_CC

Protocol Stack	Protocol
ILS Glideslope air	
	UHF 328.6 - 335.4 MHz

403

# 4044.1.3.3.9Interaction 1 Position error correction.Civil Aircraft (PJ.02-02)\_CC and405Navigation Infrastructure Satellite Based\_CC (Duplicata)

406 **System Port:** SAT\_EGNOS at Civil Aircraft\_CC

Protocol Stack	Protocol
SBAS EGNOS	
	L1 1572.42MHz

407

## 408 **System Port:** NAV\_SAT\_GNSS at Navigation Infrastructure Satellite Based\_CC

Protocol Stack	Protocol
GNSS BEIDOU	
	B1 1561.098 MHz





	B2 1207.147 MHz
	B3 1268.52 MHz
GNSS GALILEO	
	E1 1575.42 MHz
	E5a 1176.45 MHz
	E5b 1207.14 MHz
	E6 1278.75 MHz
GNSS GLONASS	
	L1 1598.0625 - 1605.375 MHz
	L2 1242.9375 - 1248.625 MHz
	L3 1201 MHz
GNSS GPS	
	L1 1575.42MHz
	L2 1227.6 MHz
	L5 1176.45 MHz
SBAS EGNOS	
	L1 1572.42MHz

# 410 **4.1.3.3.10 Interaction Controller Pilot ATC exchange(Voice).**

# 411 **System Port:** ATC\_VOICE\_MFC\_GND at TWR\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

412

## 413 **System Port:** VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2
ATC Voice (QSIG) ground	
	ATS QSIG
ATC Voice (VoIP, control) ground	





	SIP
	ТСР
	IP
ATC Voice (VoIP, media) ground	
	RTP
	UDP
	IP
OPC (Operational) Voice ground	

## 415 **System Port:** ATC\_VOICE\_MFC\_GND at TWR\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

# 416

# 417 **System Port:** VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2
ATC Voice (QSIG) ground	
	ATS QSIG
ATC Voice (VoIP, control) ground	
	SIP
	ТСР
	IP
ATC Voice (VoIP, media) ground	
	RTP
	UDP
	IP
OPC (Operational) Voice ground	

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# 418

419 System Port: ATC\_VOICE\_MFC\_GND at TWR\_CC



Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

# 421 **System Port:** VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol	
ATC Voice (MFC) ground		
	ATS MFC R2	
ATC Voice (QSIG) ground		
	ATS QSIG	
ATC Mains (Mains an anna) ann an		
ATC Voice (VoIP, control) ground		
	SIP	
	ТСР	
	IP	
ATC Voice (VoIP, media) ground		
	RTP	
	UDP	
	IP	
OPC (Operational) Voice ground		

## 422

# 423 **System Port:** ATC\_VOICE\_MFC\_GND at TWR\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2

424

# 425 System Port: VOICE\_RADIO\_GND at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice (MFC) ground	
	ATS MFC R2
ATC Voice (QSIG) ground	





	ATS QSIG
ATC Voice (VoIP, control) ground	
	SIP
	ТСР
	IP
ATC Voice (VoIP, media) ground	
	RTP
	UDP
	IP
OPC (Operational) Voice ground	

# 427 System Port: ATC\_VOICE at Civil Aircraft\_CC

Protocol Stack	Protocol
ATC Voice air	
	VHF - AM 25kHz/8.33kHz
	HF - AM 25kHz

428

# 429 **System Port:** VOICE\_RADIO\_AIR at Communication Infrastructure\_CC

Protocol Stack	Protocol
ATC Voice air	
	VHF - AM 25kHz/8.33kHz
	HF - AM 25kHz
OPC (Operational) Voice air	
	VHF
	HF (selcal)

430

431



# 433 **4.2** Functional and non-Functional Requirements

# 434 **4.2.1 Requirements for ground**

# 435 **4.2.1.1 Controller separation assistance tool**

The following requirements are common to all concepts and they all refer to the controller separation assistance tool. These requirements are common with PJ02-01 requirements relating to that support tool.

439 [REQ]

Identifier	REQ-02.01-TS-ARR1.0070
Title	Mode Change HMI
The HMI shall allow the following mode change	
Poquiromont	from DBS to TBS
Requirement	from TBS to DBS
	for each arrival runway
Status	<validated></validated>
Dationala	Controllers need to be able to activate or deactivate TBS mode on
Rationale	demand
Category	<hmi></hmi>

## 440

## 441 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

442

## 443 [REQ]

Identifier	REQ-02.01-TS-ARR1.0071	
Title	Mode Change	
Requirement	Upon each mode change, impacted TDIs shall be recomputed in consistency with the new mode applied	
Status	<validated></validated>	
Rationale	TDIs must be recomputed upon each input change	
Category		

444





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

### 447 [REQ]

Identifier	REQ-02.01-TS-ARR1.0072
Title	Mode Change Display
Requirement	The HMI shall show for each aircraft the mode of operation applied
Status	<validated></validated>
Rationale	Controllers need to be aware of the current mode of operation
Category	

448

# 449 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 450

## 451 [REQ]

Identifier	REQ-02.01-TS-ARR1.0080
Title	Runway wind
Requirement	The current Runway surface wind may be provided to the Separation delivery tool
Status	<validated></validated>
Rationale	Runway surface wind is not necessary fort TDIs computation but may increase controllers situational awareness
Category	

# 452





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

## 455 [REQ]

Identifier	REQ-02.01-TS-ARR1.0090
Title	Display Option
Requirement	The HMI may display the TDIs in different shapes depending on the type of TDI
Status	<validated></validated>
Rationale	Controllers preferences need to be taken into account by the HMI
Category	

456

# 457 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

## 458

## 459 [REQ]

Identifier	REQ-02.01-TS-ARR1.0091
Title	Hide TDIS
Requirement	The HMI shall be able to hide selected TDIs
Status	<validated></validated>
Rationale	Controller may need to unselect some displays
Category	

460

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5





<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

## 463 [REQ]

Identifier	REQ-02.01-TS-ARR1.0100	
Title	Infringement alert 1	
Requirement	An infringement alert shall be sent by the separation delivery tool to HMI as soon as the Follower aircraft established on the centerline goes beyond its targeted ITD	
Status	<validated></validated>	
Rationale	Infringement alert triggered by the separation delivery tool needs to be sent to HMI	
Category	<interoperability> , <safety></safety></interoperability>	

#### 464

## 465 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 466

## 467 [REQ]

Identifier	REQ-02.01-TS-ARR1.0101
Title	Infringement alert 2
Requirement	An infringement alert shall be sent by the separation delivery tool to HMI if both if the following conditions are met - the ORD is less than d NM - the follower aircraft established on the centerline goes beyond d NM from its targeted FTD
Status	<validated></validated>
Rationale	Controllers need to be warned if the infringement is close but undetectable because of low compression
Category	

468





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 471 [REQ]

Identifier	REQ-02.01-TS-ARR1.0102
Title	Display of infringement alert
Requirement	HMI shall display the FTD upon reception of an infringement alert on an ITD
Status	<validated></validated>
Rationale	Infringement alert of the ITD is needed to be displayed
Category	

472

# 473 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 474

## 475 [REQ]

Identifier	REQ-02.01-TS-ARR1.0110
Title	Distance step resolution
Requirement	The Separation Delivery tool HMI shall display indicators to at least a distance step resolution of 0.1NM
Status	<validated></validated>
Rationale	Resolution needs to be high enough to avoid lack of situational awareness
Category	

## 476





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 479 [REQ]

Identifier	REQ-02.01-TS-ARR1.0120
Title	TDI association
Requirement	The HMI shall be able to show the association between each TDI and its follower aircraft
Status	<validated></validated>
Rationale	Controllers may need to identify which aircraft is associated to each TDI
Category	

## 480

## 481 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

## 482

## 483 [REQ]

Identifier	REQ-02.01-TS-ARR1.0121
Title	TDI value
Requirement	The HMI might display the TDIs values
Status	<in progress=""></in>
Rationale	TDIs are displayed, their values may be needed for additional
Rationale	awareness
Category	<hmi></hmi>

## 484





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

## 487 [REQ]

Identifier	REQ-02.01-TS-ARR1.0122
Title	Distance to TDI
Requirement	The HMI might display the distance between TDIs and the associated follower aircraft
Status	<in progress=""></in>
Rationale	Distance values might be useful to controllers
Category	<hmi></hmi>

488

# 489 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

#### 490

## 491 [REQ]

Identifier	REQ-02.01-TS-ARR1.0130
Title	Display approach arrival sequence
Requirement	The HMI may display the approach arrival sequence on all CWPs
Status	<validated></validated>
Rationale	Approach arrival sequence is an additional information needed by the ATCO
Category	<hmi></hmi>

#### 492

Relationship	Linked Element Type	Identifier





<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

## 495 [REQ]

Identifier	REQ-02.01-TS-ARR1.0140
Title	Wind display
Requirement	CWPs HMI may display glideslope and surface wind information
Status	<in progress=""></in>
Rationale	Wind information may be useful to approach controllers
Category	<hmi></hmi>

496

## 497 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

## 498

## 499 [REQ]

Identifier	REQ-02.01-TS-ARR3.0020
Title	List of approaches
Requirement	For each aircraft, the expected and cleared approach procedure selected by the approach controller shall be communicated to the separation delivery tool in order to use the appropriate separation minima between the leader and follower aircraft.
Status	<in progress=""></in>
Rationale	The separation delivery tool needs inputs related to all applicable enhanced approach procedures
Category	<hmi></hmi>

500

Relationship	Linked Element Type	Identifier





<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

## 503 [REQ]

Identifier	REQ-02.01-TS-ARR3.0021
Title	Offline tables
Requirement	The separation delivery tool shall be provided with the approach separation minima for each combination of published approach procedure (i.e. GLS Z 32R or ILS Y 32R) with different glideslopes, which takes into account the associated navigation means and corresponding vertical accuracy around the published profile.
Status	<in progress=""></in>
Rationale	The separation delivery tool needs inputs related to all applicable enhanced approach procedures
Category	<data></data>

#### 504

# 505 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1204
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1205

#### 506

## 507 [REQ]

Identifier	REQ-02.01-TS-ARR3.0022
Title	Air Speed profiles
Requirement	For each aircraft, the system shall include offline defined air speed profiles for each of the procedures applicable to this aircraft among the following ILS VFR IGS SRAP CSPR-DT A-IGS IGS-to-SRAP.
Status	<in progress=""></in>
Rationale	The separation delivery tool needs inputs related to all applicable





enhanced		enhanced approach procedures
	Category	<data></data>

# 509 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

## 510

## 511 [REQ]

Identifier	REQ-02.01-TS-ARR3.0023	
Title	EAP TDI's recomputation for leader	
Requirement	Upon confirmed change of approach procedure for aircraft A, and if A has a leader in the arrival sequence, the system shall recompute the TDIs targeted by A, updating - the separation table taking into account aircraft A's leader approach and aircrafts A's new selected approach and - the new speed profile for aircraft A corresponding to its new selected approach	
Status	<validated></validated>	
Rationale	TDIs must be updated upon any input change	
Category		

# 512

# 513 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

# 514

Identifier	REQ-02.01-TS-ARR3.0024	
Title	EAP TDI's recomputation for follower	





Requirement	Upon confirmed change of approach procedure for aircraft A, and if A has a follower in the arrival sequence, the system shall recompute the TDIs of aircraft A, updating - the separation table taking into account aircraft A's new approach and aircraft A's follower approach and - the new speed profile for aircraft A corresponding to its new selected approach
Status	<validated></validated>
Rationale	TDIs must be updated upon any input change
Category	<functional></functional>

# 517 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

### 518

## 519 [REQ]

Identifier	REQ-02.01-TS-ARR3.0030	
Title	Visual Approach	
Requirement	Upon a Visual Approch clearance for aircraft A, CWP HMI shall inhibit the display of the following indications - ITD display - FTD display - Catch-up alert - Speed alert - Infringement alert	
Status	<validated></validated>	
Rationale	Visual approach separation is under pilot's responsibility	
Category	<hmi></hmi>	

#### 520

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104





<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

# 523 [REQ]

Identifier	REQ-12.02.02-TS-INT1.0010	
Title	Input Wind format for separation	
Requirement	The separation delivery tool shall receive at each online update the following wind data for each Runway and for each predefined altitude layer - current heading to apply - current speed to apply from the MET data provider	
Status	<validated></validated>	
Rationale	heading and speed are needed to be provided to the separation delivery tool	
Category		

#### 524

# 525 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 526

# 527 [REQ]

Identifier	REQ-12.02.02-TS-INT1.0011	
Title	Input wind format for prediction	
Requirement	The system supporting the separation delivery tool should receive the following wind data - forecast heading - forecast speed from the MET data provider	
Status	<in progress=""></in>	
Rationale	MET data are necessary for separation provision	
Category	<interoperability></interoperability>	

# 528





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

#### 531 [REQ]

Identifier	REQ-12.02.02-TS-INT1.0012	
Title	Runway surface wind	
Requirement The MET data provider shall send the current runway surface heading and wind speed to the separation delivery tool		
Status	<validated></validated>	
Rationale	MET current data are necessary for separation provision	
Category		

532

# 533 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

#### 534

# 535 [REQ]

Identifier	REQ-12.02.02-TS-INT1.0013	
Title	Forecast runway surface wind	
Requirement	The MET data provider shall send the forecast runway surface wind heading and wind speed to the separation delivery tool	
Status	<in progress=""></in>	
Rationale	MET forecast data are necessary for separation provision	
Category	<interoperability></interoperability>	

# 536

Relationship	Linked Element Type	Identifier





<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

## 539 [REQ]

Identifier	REQ-12.02.02-TS-INT1.0020	
Title	Traffic data	
Requirement	The surveillance system shall provide - a unique identifier - a position value - altitude information - ground speed to each arrival aircraft that is correlated in the traffic	
Status	<validated></validated>	
Rationale	Aircraft live track data in appropriate category is necessary for display on the HMI	
Category		

# 540

## 541 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 542

Identifier	REQ-12.02.02-TS-INT1.0030	
Title	Flight data	
	The Flight Data Processing shall provide	
	- a unique identifier	
Requirement - aircraft type		
	- wake category	
	to each arrival aircraft that is correlated in the traffic	
Status	<validated></validated>	
Rationale	Aircraft live FPL data in appropriate category is necessary for	





		display on the HMI
Cate	gory	

# 545 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 546

## 547 [REQ]

Identifier	REQ-12.02.02-TS-INT1.0040	
Title	Runway Intent	
Requirement	Each aircraft's runway intent shall be provided by the Flight Data Processing	
Status	<validated></validated>	
Rationale	Aircraft live FPL data in appropriate category is necessary for display on the HMI	
Category		

# 548

## 549 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

550

Identifier	REQ-12.02.02-TS-OPS1.0010	
Title	Wake separation provision	
Requirement	The system shall allow to define wake separation tables among the following - ICAO	





	- RECAT-EU
	- RECAT-2
	- WDS
Status	<validated></validated>
Rationale	Necessary inputs to the separation delivery tool must be offline configurable
Category	

# 553 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 554

# 555 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0020	
Title	Wake separation value	
	Wake separations values shall be provided to the system both	
Requirement	- in distance and	
	- in corresponding time to fly	
Status	<validated></validated>	
Rationale	Safety separations to apply need to be input to the separation	
	delivery tool	
Category		

### 556

## 557 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

558





Identifier	REQ-12.02.02-TS-OPS1.0021	
Title	MRS value	
Requirement	Offline modifiable Minimum Radar Separation values shall be provided to the system	
Status	<validated></validated>	
Rationale	Safety separations to apply need to be input to the separation delivery tool	
Category		

#### 561 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

## 562

#### 563 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0022
Title	Runway Spacing
Requirement	Offline modifiable specific Spacing values shall be provided to the system
Status	<validated></validated>
Rationale	Specific separations to apply need to be input to the separation delivery tool
Category	

#### 564

# 565 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

566





Identifier	REQ-12.02.02-TS-OPS1.0030	
Title	Buffer for uncertainties on wind and speed profile	
Requirement	The system shall be provided with offline defined "buffer" separation values - in distance for DBS mode and in time for TBS mode - representing combined impact of the uncertainties for aircraft air speed profile and glideslope wind values	
Status	<validated></validated>	
Rationale	Uncertainties need to be taken into account for safety matters	
Category		

# 569 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

### 570

## 571 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0040	
Title	TDIs transmission in all modes	
Requirement	The system shall send to CWP HMI the TDIs values for each pair of arriving aircraft in the sequence for one selected mode among the following TBS WDS S-PWS	
Status	<validated></validated>	
Rationale	Controllers need to visualize separations to apply	
Category		

572

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105





# 575 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0050	
Title	TDIs display	
Requirement	The CWP HMI shall be able to display the TDIs sent by the system	
Status	<validated></validated>	
Rationale	Controllers need to visualize separations to apply	
Category		

576

# 577 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

#### 578

## 579 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0060	
Title	Aircraft Data	
Requirement	<ul> <li>The Separation delivery tool shall be provided with the following online data for each aircraft in the traffic</li> <li>ICAO Aircraft Type</li> <li>Wake Turbulence Category</li> <li>True air speed profile on the final glide slope</li> <li>Runway Ocupancy Time</li> <li>Runway Intent</li> </ul>	
Status	<validated></validated>	
Rationale	Aircraft offline data in appropriate category is necessary for display on the HMI	
Category	<data> , <interoperability></interoperability></data>	

580

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105





<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

# 583 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0061	
Title	Traffic data	
Requirement	The System shall be provided with the following online data for each aircraft, updated at each system timestamp - position - altitude - time of the system- current ground speed	
Status	<validated></validated>	
Rationale	Aircraft live track data in appropriate category is necessary for display on the HMI	
Category	<data> , <interoperability></interoperability></data>	

584

## 585 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

# 586

## 587 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0070
Title	FTD computation with constraints
Requirement	For each pair of arrivaing aircraft, in case one set of TDIs is computed by the system, the FTD shall take the value of of the greatest separation constraints among ROT, Gap request, MRS, Wake separation and any other offline defined specific separation involving one of the aircraft in the pair
Status	<validated></validated>
Rationale FTD represents the most constraining separation to respendent between 2 consecutive aircraft	
Category	

588





### 589 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

## 590

#### 591 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0071
Title	Second FTD computation with constraints
Requirement	For each pair of arrivaing aircraft, in case a second set of TDIs is computed by the system (infringement of Gap or ROT ITD), the FTD of the second set shall take the value of of the greatest separation constraints among MRS and Wake separation.
Status	<validated></validated>
Rationale	Safety critical separation need to be displayed even if not the most constraining separation
Category	

592

# 593 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

594

Identifier	REQ-12.02.02-TS-OPS1.0080	
Title	Arrival Sequence	
	The system shall be provided with the online current arrival	
	sequence, updated at least at each change in the sequence among	
Requirement	the following	
Requirement	- Aircraft removed from the sequence	
	- Aircraft added in the sequence	
	- Change of index of an Aircraft in the sequence	





	- Runway Intent for each aircraft in the sequence	
Status	<validated></validated>	
Rationale	Any update in the sequence needs to be sent to the separation delivery tool	
Category	<interoperability> , <functional></functional></interoperability>	

# 597 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

598

## 599 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0090	
Title	Required data for FTD computation in TBS mode	
Requirement	For a pair of consecutive arriving aircraft (Leader;Follower), the system shall compute the FTD based on the following data - Glide slope wind data (strength and direction) - Wake separation value to apply (in time or distance depending on the chosen mode) - Leader's ROT - Follower's Air Speed Profile - MRS value - Any potential Gap request behind the leader	
Status	<validated></validated>	
Rationale	FTD computation needs all applicable constraints	
Category		

600

# 601 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

602





# 603 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0091
Title	Required data for ITD computation in TBS mode
Requirement	For a pair of consecutive arriving aircraft (Leader;Follower), the system shall compute the ITD based on the following data - Glide slope wind data (strength and direction) - FTD position - Follower's Air Speed Profile - Leader's Air Speed profile
Status	<validated></validated>
Rationale	ITD needs wind and speed information on top of FTD data
Category	

604

# 605 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

606

## 607 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0100	
Title	Required data for FTD update in TBS mode	
Requirement	For a pair of consecutive arriving aircraft (Leader;Follower), the system shall update the FTD upon any online change among the following data - Glide slope wind data (strength and direction) - Wake separation value to apply - Leader's ROT - Follower's Speed Profile - MRS value - Any potential Gap request behind the leader - Leader's position	
Status	<validated></validated>	
Rationale	TDIs must be updated upon any input change	
Category		

608





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1206

## 611 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0101	
Title	Required data for ITD update in TBS mode	
Requirement	For a pair of consecutive arriving aircraft (Leader;Follower), the system shall update the ITD upon any online change among the following data - Glide slope wind data (strength and direction) - Wake separation value to apply - Leader's ROT - Leader's True Air Speed profile on the glideslope - Follower's True Air Speed Profile on the glideslope - MRS value - Any potential Gap request behind the leader - FTD position	
Status	<validated></validated>	
Rationale	TDIs must be updated upon any input change	
Category	<functional></functional>	

### 612

## 613 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 614

Identifier	REQ-12.02.02-TS-OPS1.0102
Title	Sequence change
Requirement	For each pair of consecutive arriving aircrafts,(Leader ; Follower), if either the Leader or the Follower changes, TDIs shall be recomputed at the next update
Status	<validated></validated>
Rationale	TDIs must be updated upon any input change





## 617 [REQ Trace]

Category

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

### 618

# 619 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0103
Title	Sequence arrival
Requirement	One arrival sequence per runway shall be provided to the Separation delivery tool
Status	<validated></validated>
Rationale	Each runway needs one and only one sequence as input
Category	

620

# 621 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

622

Identifier	REQ-12.02.02-TS-OPS1.0110
Title	ITD greater than FTD
Requirement	For a pair of (Leader;Follower) aircraft, if the initially computed ITD value is smaller that the FTD, the ITD shall automatically take the same value as the FTD
Status	<validated></validated>
Rationale	FTD is the minimum applicable separation between 2 consecutive aircraft





## 625 [REQ Trace]

Category

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

#### 626

# 627 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0120
Title	Wake separation Definition for DBS mode
Requirement	In any DBS mode – ICAO, RECAT-EU or S-PWS - the wake constraint shall match the distance to fly defined in the separation table
Status	<validated></validated>
Rationale	Offline data and displayed data need to be consistent in time and in distance
Category	<functional></functional>

#### 628

# 629 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

# 630

Identifier	REQ-12.02.02-TS-OPS1.0121	
Title	Wake separation Definition for TBS mode	
Requirement	In any TBS and WDS mode – ICAO, RECAT-EU or S-PWS - the wake constraint shall match the time to fly defined in the separation table	
Status	<validated></validated>	





Rationale	Offline data and displayed data need to be consistent in time and in distance
Category	

## 633 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

## 634

# 635 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0130	
Title	TDIs display on the centerline 1	
Requirement	TDIs shall be displayed on the extended centerline at the correct distance (FTD and ITD) behind the Leader.	
Status	<validated></validated>	
Rationale	Controllers need an aiming point on the extended centreline	
Category	<functional></functional>	

# 636

# 637 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

# 638

Identifier	REQ-12.02.02-TS-OPS1.0131	
Title	TDIs display on the centerline 2	
Requirement	If	
	- the Leader aircraft is eligible for TDIs display	
	- the Leader aircraft is not established on the centerline	
	- the Leader aircraft's projected position on the centerline is	





	behind its targeted ITD	
	Then its TDIs shall be displayed on the extended centerline at the correct distance behind the projected position of the Leader on the extended centerline	
Status	<validated></validated>	
Rationale	Controllers need an aiming point on the extended centreline	
Category		

# 641 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 642

# 643 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0132
Title	TDIs display on the centerline 3
Requirement	If - the Leader aircraft is eligible for TDIs display - the Leader aircraft is not established on the centerline - the Leader aircraft's projected position on the centerline is in front of its targeted ITD Then its TDIs shall be displayed on the extended centerline at the correct distance behind the position of the leader's ITD on the extended centerline
Status	<validated></validated>
Rationale	Controllers need an aiming point on the extended centreline
Category	

644

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105





## 647 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0140	
Title	Speed conformance alert	
Requirement	The Separation Delivery Tool shall send to CWP HMI a speed conformance alert when an aircraft's ground speed exceeds its offline defined air speed - corrected by the wind value - by a predefined offline tolerance value	
Status	<validated></validated>	
Rationale	Controller needs to aware of any inconsistency between offline data and real data	
Category		

## 648

# 649 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

### 650

# 651 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0150
Title	Catch-up alert
Requirement	The Separation delivery tool may send a catch-up alert to the HMI when a follower aircraft is expecting to reach the ITD in less than T seconds, T being an offline defined parameter.
Status	<validated></validated>
Rationale	Controller may need to be aware of any potential separation infringement in the near future
Category	

652

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1107





## 655 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0160	
Title	Sequence alert	
Requirement	The separation delivery tool shall send a sequence alert to the HMI when the order of arrival in the arrival sequence list differs from the order of aircraft position on the extended runway centerline starting from the Runway threshold	
Status	<validated></validated>	
Rationale	Sequence order on the final approach need to be correct for safety	
Category	<safety></safety>	

## 656

# 657 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

# 658

# 659 [REQ]

Identifier	REQ-12.02.02-TS-OPS1.0170
Title	System failure
Requirement	The separation delivery tool shall send to the HMI an error message in case of system failure
Status	<in progress=""></in>
Rationale	Controllers need to be aware of any system failure
Category	<safety></safety>

660

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104





<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
	s in this negative inclusion	REQ 11.5 STRIPPEROF CIE.1105

# 663 [REQ]

Identifier	REQ-02.01-TS-ARR1.0011	
Title	Sending Aircraft distance to FTD	
Requirement	For each aircraft in the arrival sequence which has a leader aircraft in the arrival sequence, the system shall send the distance value between the aircraft and its targeted FTD to the Tower CWP and to the Approach CWP.	
Status	<validated></validated>	
Rationale	Distance Aircraft - FTD can improve situational awareness for controllers	
Category	<hmi> , <interoperability></interoperability></hmi>	

#### 664

### 665 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

# 666

## 667 [REQ]

Identifier	REQ-02.01-TS-ARR1.0010
Title	Display of Aircraft distance to FTD
Requirement	If an aircraft is - eligible for TDIs display - established on the centerline - infringing its targeted ITD, and the separation delivery tool shall send the distance value between the aircraft and the targeted FTD to the HMI
Status	<validated></validated>
Rationale	If the aircraft has infringed ITD, Tower CWP needs to display distance to FTD to verify that the aircrafts does not go beyond the FTD
Category	<hmi> , <interoperability></interoperability></hmi>

668





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

#### 671 [REQ]

Identifier	REQ-02.01-TS-ARR1.0020
Title	Gap HMI input
Requirement	The HMI shall provide the possibility to input a gap spacing value, in distance or in time, behind any aircraft eligible for TDI computation
Status	<validated></validated>
Rationale	ATCo needs to be able to to insert a gap behind an aircraft for departure or other reason
Category	<hmi></hmi>

# 672

# 673 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

## 674

Identifier	REQ-02.01-TS-ARR1.0026
Title	Feedback following gap insertion
Requirement	The tool shall provide a feedback on whether or not the gap insertion or update is successful
Status	<in progress=""></in>
Rationale	Several reasons could lead to the gap insertion to fail, such as insufficient time between two aircrafts on the centre line for the gap value to be inserted, etc.
Category	<functional></functional>





# 677 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

#### 678

# 679 [REQ]

Identifier	REQ-02.01-TS-ARR1.0021	
Title	Gap transmission	
Requirement	Upon reception of a gap spacing instruction behind an aircraft, CWP HMI shall send the instruction along with the value to the Separation delivery tool	
Status	<in progress=""></in>	
Rationale	Self explanatory	
Category	<interoperability> , <hmi></hmi></interoperability>	

#### 680

## 681 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

#### 682

## 683 [REQ]

Identifier	REQ-02.01-TS-ARR1.0023	
Title	Gap HMI cancel	
Requirement	The HMI shall provide the possibility to cancel a gap spacing value previously requested for an aircraft.	
Status	<validated></validated>	
Rationale	ATCo needs to be able to to cancel a gap behind an aircraft	
Category	<hmi></hmi>	

684





# 685 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

# 686

## 687 [REQ]

Identifier	REQ-02.01-TS-ARR1.0024	
Title	Gap cancel recomputation	
Requirement	Upon reception of a gap cancel instruction behind an aircraft, the system shall recompute the TDIs attached to the concerned aircraft taking into account the absence of Gap constraint	
Status	<validated></validated>	
Rationale	Self explanatory	
Category	<functional></functional>	

## 688

# 689 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

# 690

# 691 [REQ]

Identifier	REQ-02.01-TS-ARR1.0030
Title	Constraint information transmission
Requirement	For each aircraft, the system shall send to Tower and Approach CWP HMI the constraint type MRS, or GAP, or WAKE, or ROT along with the sent TDIs
Status	<validated></validated>
Rationale	HMI must be able to dispolay the chevron differently taking into account the associated constraint
Category	<interoperability></interoperability>

692





# 693 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

# 694

## 695 [REQ]

Identifier	REQ-02.01-TS-ARR1.0031
Title	TDIs display with constraint
Requirement	The Tower CWP HMI and the Approach CWP HMI shall be able to apply different shapes to the displayed TDIs taking into account the applied constraint
Status	<validated></validated>
Rationale	ATCO must be able to differenciate the constraint behind the TDIs
Category	<hmi></hmi>

# 696

# 697 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

# 698

Identifier	REQ-02.01-TS-ARR1.0040	
Title	TDIs computation WAKE and MRS	
Requirement	If the most constraining separation type is of ROT or GAP type, then the system shall automatically compute a second set of TDIs related to the most constraining separation value between MRS and WAKE.	
Status	<in progress=""></in>	
Rationale	System must be able to send the Safety constaint behind non safety constraints	
Category	<functional></functional>	





# 701 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

# 702

# 703 [REQ]

Identifier	REQ-02.01-TS-ARR1.0041	
Title	TDIs display WAKE and MRS	
Requirement	If an infringement event is triggered on an ITD representing ROT or GAP constraint, the CWP HMI shall display the ITD related to related to the second set of TDIs sent by the System.	
Status	<in progress=""></in>	
Rationale	ATCO needs to know what is the Safety constraintbehind the non safety constraint	
Category	<hmi></hmi>	

# 704

# 705 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

706

Identifier	REQ-02.01-TS-ARR1.0050	
Title	Runway change	
Requirement	The HMI shall allow each aircraft in one arrival sequence to be assigned to another arrival sequence corresponding to a different runway.	
Status	<validated></validated>	
Rationale	ATCO needs to have the possibility to change the assigned runway	





[		for al aircrafts
	Category	<interoperability> , <hmi></hmi></interoperability>

# 709 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

## 710

## 711 [REQ]

Identifier	REQ-02.01-TS-ARR1.0060	
Title	CSPR offline	
RequirementThe offline configuration file for the system shall allow to sp 2 runways are CSPR or not		
Status	<in progress=""></in>	
Rationale	Offline configuration of CSPR	
Category	<data></data>	

# 712

# 713 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105

714

Identifier	REQ-02.01-TS-ARR1.0061
Title	CSPR application
Requirement	For each pair of consecutive arrivals on 2 CSPR the TDIs shall apply an additional longitudinal constraint of a configurable minimum longitudinal separation between the 2 aircrafts.
Status	<in progress=""></in>
Rationale	Computation of TDIs in CSPR





Category	<functional></functional>

# 717 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106

# 718 **4.2.1.1.1 Other ground requirements**

# 719 [REQ]

Identifier	REQ-14.5-TS-GND-0001	
Title Expected Approach procedure selection by Approach Execu Controller		
Requirement	For each arrival traffic, the flight label on ATC display should enable the Approach Executive Controller to select the expected approach procedure, among the list of active approach procedures being eligible for this traffic (e.g. based on the traffic navigation guidance capabilities declared in the flight plan), and then to record it.	
Status	<validated></validated>	
Rationale	Self explanatory	
Category	<functional> , <hmi> , <safety> , <design></design></safety></hmi></functional>	

#### 720

# 721 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1006
<allocated_to></allocated_to>	<function></function>	Identify Eligible Approach Procedures Request Eligible Approach Procedures

### 722

Identifier	REQ-14.5-TS-GND-0002
Title	Expected approach procedure display
Requirement	The selected expected approach procedure should be displayed in





	the flight label and/or flight plan information.
Status	<validated></validated>
Rationale	Self explanatory
Category	<functional> , <hmi> , <safety> , <design></design></safety></hmi></functional>

# 725 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1006
<allocated_to></allocated_to>	<function></function>	Display Eligible Approach Procedures

# 726

# 727 [REQ]

Identifier	REQ-14.5-TS-GND-0003
Title	Cleraed Approach procedure selection by Approach Executive Controller
Requirement	For each arrival traffic, the flight label on ATC display should enable the Approach Executive Controller to select the cleared approach procedure among the list of active approach procedures eligible for that aircraft, not necessarily the expected one previously recorded, and then to record it.
Status	<validated></validated>
Rationale	Self explanatory
Category	<design> , <safety> , <functional> , <hmi></hmi></functional></safety></design>

# 728

# 729 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1015
<allocated_to></allocated_to>	<function></function>	Record Approach Procedure Information

730

Identifier	REQ-14.5-TS-GND-0004
Litle	Distinct display of expected and cleared approach procedures for Approach Executive Controller
Requirement	Expected and cleared approach procedures shall be displayed in





	distinct ways so that the Approach Executive Controller can easily and unambiguously distinguish aircraft already cleared from the others.
Status	<validated></validated>
Rationale	Self explanatory
Category	<design> , <hmi> , <functional> , <safety></safety></functional></hmi></design>

## 733 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1006
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1015

#### 734

# 735 [REQ]

Identifier	REQ-14.5-TS-GND-0005
Title	Update of expected approach procedure by Approach Executive Controller
Requirement	The flight label on ATC display shall enable the Approach Executive Controller to update the expected approach procedure by selecting a different one among the list of active approach procedures eligible for that aircraft.
Status	<validated></validated>
Rationale	Self explanatory
Category	<functional> , <safety> , <design> , <hmi></hmi></design></safety></functional>

## 736

# 737 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1017
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1016
<allocated_to></allocated_to>	<function></function>	Display Eligible Approach Procedures

#### 738

REQ-14.5-15-GND-0006	Identifier	
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Title	Display of Wake Turbulence Category (WTC) for Approach and Tower Controller
Requirement	Where a separation tool is used, the Wake Turbulence Category (WTC) shall remain displayed to the Approach and Tower Controller with the flight label
Status	<validated></validated>
Rationale	Self explanatory
Category	<functional> , <design> , <hmi> , <safety></safety></hmi></design></functional>

# 741 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1106
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1104

#### 742

744

746

#### 743 [REQ]

Identifier	REQ-14.5-TS-GND-0007
Title	Guidance for Approach Executive Controller's screen
Requirement	The ATC system HMI adaptations shall not clutter the Approach Executive Controller's screen, and shall follow human factor design best practices.
Status	<validated></validated>
Rationale	Self explanatory
Category	<design> , <hmi> , <functional> , <safety></safety></functional></hmi></design>

# 745 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1109

Identifier	REQ-14.5-TS-GND-0008	
Title	Final approach interception location references display for Approach Executive Controller	
Requirement	Final approach interception location references should be	





	displayed on the Approach Executive Controller display, according to local assessment.
Status	<validated></validated>
Rationale	Self explanatory
Category	<design> , <safety> , <functional> , <hmi></hmi></functional></safety></design>

## 749 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1109
<allocated_to></allocated_to>	<function></function>	Monitor and Separate Traffic (IGS-to-SRAP)

# 751 [REQ]

750

Identifier	REQ-14.5-TS-GND-0009
Title	Alerting function for Approach Executive Controller for detecting non compliance to assigned profile
Requirement	An alerting function shall warn the Approach Executive Controller for detecting situations when an aircraft is not complying / is deviating from the assigned published final approach profile, among multiple active approach procedures.
Status	<in progress=""></in>
Rationale	Self explanatory
Category	<safety> , <functional></functional></safety>

#### 752

## 753 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1108

754

Identifier	REQ-14.5-TS-GND-0010
Title	Arrival sequencing optimisation function to Approach Executive Controller
Requirement	An arrival sequencing optimisation function should assist the Approach Executive Controller in proposing the optimum approach procedure for each aircraft, taking into account the active approach procedures and aircraft capabilities, in order to





	optimise the sequence.
Status	<in progress=""></in>
Rationale	Self explanatory
Category	<functional> , <performance></performance></functional>

# 757 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1112

758

# 759 [REQ]

Identifier	REQ-14.5-TS-GND-0011
Title	Arrival sequencing optimisation role to Approach Executive Controller
Requirement	An arrival sequencing optimisation role should assist the Approach Executive Controller in proposing the optimum approach procedure for each aircraft, taking into account the active approach procedures and aircraft capabilities, in order to optimise the sequence.
Status	<in progress=""></in>
Rationale	Self explanatory
Category	<performance> , <functional></functional></performance>

760

## 761 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1112

762

Identifier	REQ-14.5-TS-GND-0012	
Title	Training/briefing on IGS-to-SRAP procedures	
Requirement	Approach Executive Control and Tower Runway Control shall be briefed and trained on how to conduct IGS-to-SRAP operations, and the impact compared to conventional approaches with regards to e.g. changes to the separation minima, working methods, impact on speed management instructions, new	





	interception points, change to visual aids	
Status	<validated></validated>	
Rationale	Self explanatory	
Category	<safety></safety>	

# 765 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1005
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1008
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1007
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1014
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1013
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1113
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GALT.0001
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GALT.0002
<allocated_to></allocated_to>	<role></role>	ATC Executive Controller (PJ.02-W2-14.5) Tower Runway Controller (PJ.02-W2-14.5)

766

## 767 [REQ]

Identifier	REQ-14.5-TS-GND-0013
Title	Training on non nominal cases and degraded modes linked to IGS-
	to-SRAP procedures
	Approach Executive Control, Tower Runway Control and Supervisors, including new recruits, shall be trained as appropriate to apply the revised contingency procedures in case of non-
Requirement	nominal or degraded modes of operations (see list of hazards), including skills to work without separation indicators as necessary under application of degraded modes/contingency procedures (e.g. with manual application of simplified separation scheme)
Status	<validated></validated>
Rationale	Self explanatory
Category	<safety></safety>

768





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1011
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1010
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GALT.0001
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GALT.0002
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GALT.0003
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GALT.0004
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GOAR.0001
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GOAR.0002
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ORDF.0001
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ORDF.0002
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ORDF.0003
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ORDF.0004
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ORDF.0005
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ORDF.0006
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ORDF.0007
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ORDF.0008
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ORDF.0009
<allocated to=""></allocated>	<role></role>	ATC Executive Controller (PJ.02-W2-14.5)
		Tower Runway Controller (PJ.02-W2-14.5)

## 771 [REQ]

Identifier	REQ-14.5-TS-GND-0014	
Title	Particular training for vectoring for IGS-to-SRAP	
Requirement	Training of Approach Executive Control shall consider the need for vectoring the aircraft onto ITSR approach such as to avoid final approach interception from above	
Status	<validated></validated>	
Rationale	Self explanatory	
Category	<safety></safety>	

772





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1009

# 775 [REQ]

Identifier	REQ-14.5-TS-GND-0015
Title	Runway marking for IGS-to-SRAP
Requirement	IGS-to-SRAP runway marking shall consist of a set of threshold markings, aiming point markings, touch down zone (TDZ) markings
Status	<in progress=""></in>
Rationale	Self explanatory
Category	<interoperability> , <design> , <safety></safety></design></interoperability>

#### 776

#### 777 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-APT.1301

778





#### 780 [REQ]

Identifier	REQ-14.5-TS-GND-0016	
Title	Threshold, aiming point and TDZ markings for IGS-to-SRAP	
Requirement	The threshold marking, aiming point marking and TDZ markings shall be distinctive from the markings associated to the first runway threshold, and with a design being as close as possible to applicable regulatory requirements and provisions for runway markings (Annex 14).	
Status	<in progress=""></in>	
Rationale	Self explanatory	
Category	<interoperability> , <safety> , <design></design></safety></interoperability>	

# 781

# 782 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-APT.1301
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-APT.1302

#### 783

#### 784 [REQ]

Identifier	REQ-14.5-TS-GND-0017
Title	Identification of second threshold for IGS-to-SRAP
Requirement	The second threshold shall be identified with a specific runway identifier (e.g. with an increment of one unit between the first and second threshold, or use of an specific letter in addition of the runway identifier
Status	<in progress=""></in>
Rationale	Self explanatory
Category	<performance> , <safety> , <design> , <functional></functional></design></safety></performance>

#### 785

#### 786 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-APT.1301

787





#### 789 [REQ]

Identifier	REQ-14.5-TS-GND-0018	
Title	Approach lighting system for IGS-to-SRAP	
Requirement	The approach lighting system of the second threshold shall be distinctive from the one of the first threshold (e.g using a static or switching lighting system), with a design being as close as possible to applicable regulatory requirements and provisions for runway markings (Annex 14)	
Status	<in progress=""></in>	
Rationale	Self explanatory	
Category	<interoperability> , <safety> , <design></design></safety></interoperability>	

### 790

#### 791 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-APT.1301
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-APT.1302
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-APT.1303
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-APT.1304

#### 792

#### 793 [REQ]

Identifier	REQ-14.5-TS-GND-0019
Title	PAPI/VASI for IGS-to-SRAP
Requirement	PAPI/VASI shall provide appropriate landing visual guidance when flying on a SRAP approach (e.g. second PAPI in addition of the one for conventional approach, preferably located on the other side of the runway)
Status	<in progress=""></in>
Rationale	Self explanatory
Category	<design> , <safety> , <interoperability></interoperability></safety></design>

794

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-APT.1301





#### 797 [REQ]

Identifier	REQ-14.5-TS-GND-0020
Title	Update of cleared approach procedure by Approach Executive Controller
Requirement	The flight label on ATC display shall enable the Approach Executive Controller to update the cleared approach procedure by selecting a different one among the list of active approach procedures eligible for that aircraft.
Status	<validated></validated>
Rationale	Self explanatory
Category	<safety> , <functional> , <hmi> , <design></design></hmi></functional></safety>

798

#### 799 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1016
<allocated_to></allocated_to>	<role></role>	ATC Executive Controller (PJ.02-W2-14.5)

800

#### 801 [REQ]

Identifier	REQ-14.5-TS-GND-0021
Title	Check the aircraft vertical position
Requirement	A tool should allow the Approach Executive Controller to check the vertical position of an aircraft.
Status	<in progress=""></in>
Rationale	That tool would allow the controller identify an aircraft intercepting the wrong glide or an aircraft initiating a missed approach.
Category	<functional> , <hmi></hmi></functional>

802

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GOAR.0003
<allocated_to></allocated_to>	<role></role>	ATC Executive Controller (PJ.02-W2-14.5)





# **4.2.2 Requirements for aircraft systems**

### 805 4.2.2.1 IGS to SRAP airborne function

806 The following requirements apply to aircraft systems supporting IGS to SRAP concept.

#### 807 [REQ]

Identifier	REQ-14.5-TS-ACFT-0001
Title	SRAP training
Requirement	The Flight Crew shall be trained for managing and flying SRAP operations
Status	<in progress=""></in>
Rationale	e.g. SRAP principles, differences in visual references, etc
Category	<functional></functional>

808

#### 809 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2103
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2105
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2108
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2109

#### 810

#### 811 [REQ]

Identifier	REQ-14.5-TS-ACFT-0002
Title	IGS training
Requirement	The Flight Crew shall be trained for managing and flying IGS operations
Status	<validated></validated>
Rationale	e.g. IGS principles, differences in visual references, etc
Category	<functional></functional>

#### 812

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5





<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2101
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2102
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2104
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2103
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2108
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2109
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-GOAR.0004

#### 815 [REQ]

Identifier	REQ-14.5-TS-ACFT-0003
Title	Operational conditions for IGS (1/2)
Requirement	Aircraft Manufacturer may define per aircraft type the suitable operational conditions for flying an increase glideslope, as function of the slope angle
Status	<in progress=""></in>
Rationale	Flight crew shall be aware of the aircraft capability for IGS operations
Category	<functional> , <safety></safety></functional>

#### 816

# 817 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2101
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2102
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2108
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2103

818

Identifier	REQ-14.5-TS-ACFT-0004
Title	Operational conditions for IGS (2/2)
Requirement	Aircraft Operators should define per aircraft type the suitable operational conditions for flying an increase glideslope, as function of the slope angle
Status	<in progress=""></in>





Rationale	Flight crew shall be aware of the aircraft capability for IGS operations
Category	<safety> , <functional></functional></safety>

#### 821 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2101
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2102
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2103
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2108

#### 822

#### 823 [REQ]

Identifier	REQ-14.5-TS-ACFT-0005	
Title	IGS impact on MMEL	
Requirement	The Aircraft Manufacturer shall provide in the master minimum equipment list (MMEL) the operational impact in case a specific functionality is required by IGS operations (e.g. the energy management function and/or the flare assistance supporting function)	
Status	<in progress=""></in>	
Rationale	Flight crew shall be aware of the aircraft capability for IGS operations	
Category	<safety> , <functional></functional></safety>	

#### 824

#### 825 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2103
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2108

#### 826

Identifier	REQ-14.5-TS-ACFT-0006
Title	IGS impact on MEL





Requirement	The Aircraft Operator may provide in its minimum equipment list MEL) the operational impact in case a specific functionality is equired by IGS operations (e.g. the energy management function and/or the flare assistance supporting function)	
Status	<in progress=""></in>	
Rationale	Flight crew shall be aware of the aircraft capability for IGS operations	
Category	<functional> , <safety></safety></functional>	

### 829 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2103
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2108

#### 830

#### 831 [REQ]

Identifier	REQ-14.5-TS-ACFT-0007
Title	Flare assistant slope range
Requirement	Flare assistant shall support glideslopes up to 4.49°.
Status	<validated></validated>
Rationale	Maximum slope considered by PJ02-02 enhanced approach procedures.
Category	<design></design>

832

#### 833 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2102
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1212

834

Identifier	REQ-14.5-TS-ACFT-0008
Title	Flare assistant
Requirement	Flare assistant shall help flight crew to correctly perform flare
Status	<validated></validated>





Rationale	To avoid hard landing or long landing.
Category	<functional></functional>

## 837 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2102

838

#### 839 [REQ]

Identifier	REQ-14.5-TS-ACFT-0009
Title	Flare assistant compatibility with flight modes
Requirement	Flare assistant shall be available with manual flight only.
Status	<validated></validated>
Rationale If Flare assistant indications do not correspond to Aut actions, It could disturb the monitoring performed by crew, encourage them to takeover controls or perform around.	
Category	<design></design>

840

#### 841 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2102
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2106

842

# 843 [REQ]

Identifier	REQ-14.5-TS-ACFT-0010
Title	Flare assistant SOP
Requirement	Flare assistant shall not significantly modify current SOP.
Status	<validated></validated>
Rationale	For Human Performance reasons
Category	<functional></functional>

#### 844





Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2102

# 847 [REQ]

Identifier	REQ-14.5-TS-ACFT-0011
Title	Flare assistant compatibility with approaches
Requirement	Flare assistant should be available on any type of approaches.
Status	<validated></validated>
Rationale	For Human Performance reasons, it is important to provide a similar level of assistance whatever the type of approach
Category	<design></design>

#### 848

#### 849 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2102

#### 850

#### 851 [REQ]

Identifier	REQ-14.5-TS-ACFT-0012
Title	Energy management assistant for IGS
Requirement	Flight Crew may be assisted by an energy management function
Status	<validated></validated>
Rationale	An energy management assistance function may be useful for flying approaches under operational conditions leading to more complex management of energy dissipation (e.g. increased glide path angle, tailwind, etc)
Category	<functional></functional>

852

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2101
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2107





#### 855 [REQ]

Identifier	REQ-14.5-TS-ACFT-0013
Title	EM assistant slope range
Requirement	Energy management assistant shall support glideslopes up to 4.49°.
Status	<validated></validated>
Rationale	Maximum slope considered by PJ02-02 enhanced approach procedures
Category	<design></design>

#### 856

#### 857 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-CTL.1212
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2101

#### 858

#### 859 [REQ]

Identifier	REQ-14.5-TS-ACFT-0014	
Title	Energy management assistant	
Requirement	Energy management assistant shall help flight crew determine whether the aircraft can decelerate to be timely stabilized.	
Status	<validated></validated>	
Rationale	Flight Deck shall be able to decelerate the aircraft during final approach, even under flight conditions that reduce deceleration capability	
Category	<functional></functional>	

#### 860

#### 861 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2101

862





Identifier	REQ-14.5-TS-ACFT-0015
Title	EM compatibility with flight modes
Requirement	Energy management assistant should be available with both manual and automatic flight.
Status	<validated></validated>
Rationale	As long as the flight crew is involved in the energy management task, assistance is useful both in manual and automatic flight.
Category	<design></design>

#### 865 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2101
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2106

866

#### 867 [REQ]

Identifier	REQ-14.5-TS-ACFT-0016
Title	EM SOP
Requirement	Energy management assistant shall not significantly modify current SOP.
Status	<validated></validated>
Rationale	For Human Performance reasons
Category	<functional></functional>

868

#### 869 [REQ Trace]

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2107
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2101

870

Identifier	REQ-14.5-TS-ACFT-0017
Title	EM assistant compatibility with approaches
Requirement	Energy management assistant shall be available on any type of approaches.





Status	<validated></validated>
Rationale	For Human Performance reasons, it is important to provide a similar level of assistance whatever the type of approach
Category	<design></design>

Relationship	Linked Element Type	Identifier
<allocated_to></allocated_to>	<sesar solution=""></sesar>	PJ.02-PJ.02-W2-14.5
<satisfies></satisfies>	< ATMS Requirement>	REQ-14.5-SPRINTEROP-ACFT.2101





# **5 Implementation Options**

- PJ.02-W2-14.5 solution encompasses several technical enablers. The chapter 3.1.1 of this document
- 876 specify for each enabler if it is optional or required.
- The list of the optional enablers is given below.

EN code	EN description
A/C-01	Enhanced positioning for LPV/RNP based on Single Frequency SBAS
A/C-02a	Enhanced positioning using GBAS single frequency
A/C-04a	Flight management and guidance for Advanced RNP
A/C-04	Flight management and guidance for improved lateral navigation in approach via RNP
A/C-05a	APV Barometric VNAV
A/C-06	Flight management and guidance for LPV approach based on SBAS
A/C-56a	Flight management and guidance for Precision Approach GBAS CATII/III using GPS
A/C-86	On-board assistance to aircraft energy management
A/C-87	On-board assistance to flare
AERODROME- ATC-94	Aerodrome ATC system to support IGS-to-SRAP operations (separation delivery)
APP ATC 163	Approach ATC system to support IGS-to-SRAP operations (separation delivery)
CTE-N06	Space Based Augmentation System (SBAS)
CTE-N07a	GBAS Cat I based on Single-Constellation / Single-Frequency GNSS (GPS L1)
CTE-N07b	GBAS Cat II/III based on Single-Constellation / Single-Frequency GNSS (GPS L1)
CTE-N07	Ground Based Augmentation System (GBAS)

878 Table 5: optional enablers of solution PJ.02-W2-14.5

- A/C-01 to A/C-56a, and CTE enablers reflect the fact that SRAP can be guided by any of the means
- 881 listed.
- A/C-86 and A/C-87 may complement the training required for the AO-331 (HUM-024 Flight Crew
- training for IGS-to-SRAP approach), as they are meant to assist the pilot during a manual landing.
- They may become necessary on some aircraft types, and/or for some slope values.
- AERODROME-ATC-94 and APP ATC 163 enablers are inked to separation delivery assistance. They are
- not necessarily required if IGS-to-SRAP procedure is active when the traffic pressure if not high (at
- night, for example), when few aircraft types are coming to an airport, etc.



# **6** Assumptions

- 889 This section aims at describing the assumptions made that have an impact on the technical
- 890 specification.
- 891 The optional enabler A/C 87 (On-board assistance to flare) proposed in the scope of IGS operations is
- based on the assumption that increased glide slope operations will be possible on manual landing.





# **7 References and Applicable Documents**

# 894 **7.1 Applicable Documents**

- 895 Content Integration
- 896 1. EATMA Community pages
- 897 2. SESAR ATM Lexicon
- 898 Content Development
- 899 3. B4.2 D106 Transition Concept of Operations SESAR 2020
- 900 System and Service Development
- 901 4. 08.01.01 D52: SWIM Foundation v2
- 902 5. 08.01.01 D49: SWIM Compliance Criteria
- 903 6. 08.01.03 D47: AIRM v4.1.0
- 904 7. 08.03.10 D45: ISRM Foundation v00.08.00
- 905 8. B.04.03 D102 SESAR Working Method on Services
- 906 9. B.04.03 D128 ADD SESAR1
- 907 10. B.04.05 Common Service Foundation Method
- 908 Performance Management
- 909 11. B.04.01 D108 SESAR 2020 Transition Performance Framework
- 910 12. B.04.01 D42 SESAR2020 Transition Validation
- 911 13. B.05 D86 Guidance on KPIs and Data Collection support to SESAR 2020 transition.
- 912 14. 16.06.06-D68 Part 1 SESAR Cost Benefit Analysis Integrated Model
- 913 15. 16.06.06-D51-SESAR\_1 Business Case Consolidated\_Deliverable-00.01.00 and CBA
- 91416. Method to assess cost of European ATM improvements and technologies, EUROCONTROL915(2014)
- 916 17. ATM Cost Breakdown Structure\_ed02\_2014
- 917 18. Standard Inputs for EUROCONTROL Cost Benefit Analyses
- 918 19. 16.06.06\_D26-08 ATM CBA Quality Checklist
- 919 20. 16.06.06\_D26\_04\_Guidelines\_for\_Producing\_Benefit\_and\_Impact\_Mechanisms
- 920 Validation
- 921 21. 03.00 D16 WP3 Engineering methodology
- 922 22. Transition VALS SESAR 2020 Consolidated deliverable with contribution from Operational
   923 Federating Projects
- 924 23. European Operational Concept Validation Methodology (E-OCVM) 3.0 [February 2010]
- 925 System Engineering
- 926 24. SESAR 2020 Requirements and Validation Guidelines

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#### 927 Safety

- 928 25. SESAR, Safety Reference Material, Edition 4.0, April 2016
- 929 26. SESAR, Guidance to Apply the Safety Reference Material, Edition 3.0, April 2016
- 930 27. SESAR, Final Guidance Material to Execute Proof of Concept, Ed00.04.00, August 2015
- 931 28. SESAR, Resilience Engineering Guidance, May 2016
- 932 Human Performance
- 933 29. 16.06.05 D 27 HP Reference Material D27
- 934 30. 16.04.02 D04 e-HP Repository Release note
- 935 Environment Assessment
- 936 31. SESAR, Environment Reference Material, alias, "Environmental impact assessment as part of
- 937 the global SESAR validation", Project 16.06.03, Deliverable D26, 2014.
- 938 32. ICAO CAEP "Guidance on Environmental Assessment of Proposed Air Traffic Management
   939 Operational Changes" document, Doc 10031.

#### 940 Security

- 941 33. 16.06.02 D103 SESAR Security Ref Material Level
- 942 34. 16.06.02 D137 Minimum Set of Security Controls (MSSCs).
- 943 35. 16.06.02 D131 Security Database Application (CTRL\_S)

# 944 **7.2 Reference Documents**

- 945
- 946
   946 36. ED-78A GUIDELINES FOR APPROVAL OF THE PROVISION AND USE OF AIR TRAFFIC SERVICES
   947 SUPPORTED BY DATA COMMUNICATIONS.
- 948 37. PJ.02-W2.14.5 D4.5.002, PJ.02-W2-14.5 SPR-INTEROP/OSED V3 Final
- 949 38. PJ02-02 D2.1.04 SESAR PJ02-02 VALR, Edition 00.01.00





# 950 8 Service Description Document (SDD)

951 N/A







# 952 9 Service Technical Design Document (STDD)

953 N/A





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