

RPAS integration in airport and TMA operations

Conclusions and Recommendations from the INVIRCAT Project

SESAR 2020 SHOWCASE

#SESARShowcase



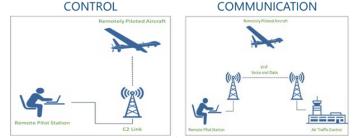
Challenges for RPAs integration





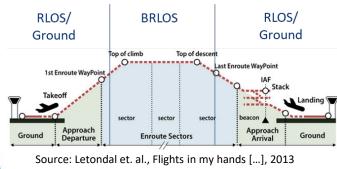
Sources: dronedj.com, Airliners HD (Youtube)

RPAS Configurations

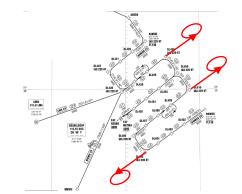


Source: ICAO Manual on RPAS, 2015

Link Architectures



Latency Aspects



RPAS Specialties in Operations



#SESARShowcase



INVIRCAT Scope

INVIRCAT developed a CONOPS for RPAS integration within the TMA and airports under IFR.

With special focus on

- Impact of latency,
- Automatic Take-off and Landing (ATOL), and



Handover of RPA control between Remote Pilot Stations



Validations

Real-time simulations

- C2 link focus
- R/T voice focus
- R/T handover focus
- ATOL focus







Operational recommendations

- Specific procedures, phraseology and training for contingency situations
- New procedures so DAA use is correctly understood and integrated
- Training for AutoTaxi and WheelTug
- The handover procedure is made known to ATC and should be outside the TMA



More in D4.3 "Final Report: Impacts and Recommendations" at <u>https://www.invircat.eu/</u>







Technical recommendations

- Identifying element/symbol for RPAS
- Report C2 link expected latency
- RPSs available at airports
- Compatibility between RPS and RPA during handover
- Indication on the ATCO HMI for simultaneous handovers of multiple RPAS



More in D4.3 "Final Report: Impacts and Recommendations" at <u>https://www.invircat.eu/</u>





Regulatory recommendations

- New ATOL and RPAS propulsion failure related regulations
- Standardization of the handover procedure
- Harmonization of C2 link failure procedures
- Back-up line in case of communication failure
- Enforcement of acceptable latency limits



More in D4.3 "Final Report: Impacts and Recommendations" at <u>https://www.invircat.eu/</u>









Visit our booth: AT-One #E19

© – 2023 – INVIRCAT Consortium. All rights reserved. Licensed to the SESAR 3 Joint Undertaking under conditions.

This project has received funding from the SESAR Joint Undertaking under the European Union's Horizon 2020 research and innovation programme under grant agreement No 893375. The opinions expressed herein reflect the author's view only. Under no circumstances shall the SESAR Joint Undertaking be responsible for any use that may be made of the information contained herein.



